EN

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B50
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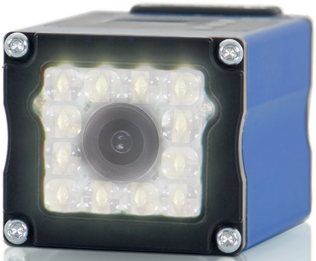
Smart Camera weQube with EtherNet/IP



EtherNet/IP™

Interface Protocol

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www.wenglor.com

Table of Contents

1. Use for Intended Purpose

The Smart Camera weQube is able to communicate with a PLC via EtherNet/IP. Thus, an exchange of process data between the Smart Camera and the PLC is possible. Furthermore, the Smart Camera sends a status to the PLC, which in turn can send commands to the Smart Camera.

NOTE!
In the manual, the EtherNet/IP integration is shown at an Allen-Bradley PLC 1769-L18E-RM-BB1B with Studio 5000 Logix Designer V32.

2. Basics about the EtherNet/IP interface of the Smart Camera

2.1 Identity Object

- Vendor ID: 1211
- Vendor Name: wenglor sensoric gmbh
- Product Type: 12 (Communications Adapter)
- Product Code: 4096
- Product Name: weqube
- Revision: 1.3

2.2 Assembly Object

- Instance 100: Configuration Assembly (Size: 12 bytes)
- Instance 101: Input Assembly (Data size depends on configuration)
- Instance 102: Output Assembly (Data size depends on configuration)

2.3 Configuration Object

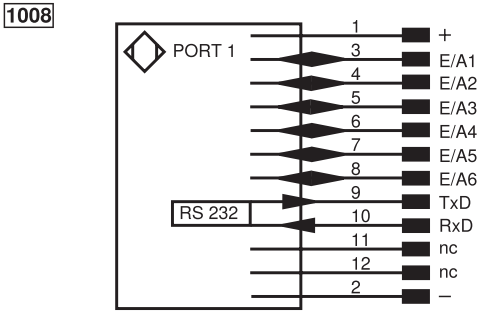
CLASS 1 connection with:
- Config 1: Module ID of Project Number
- Config 2: Module ID of Device Status
- Config 3: Module ID of Slot #3
- Config 4: Module ID of Slot #4
- Config 5: Module ID of Slot #5
- Config 6: Module ID of Slot #6

NOTE!
Only CLASS 1 connections are supported (no CLASS 3 connections)!

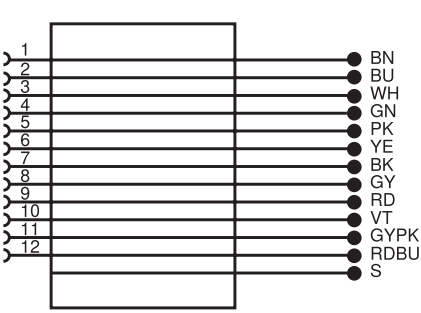
NOTE!
For not used slots, the Module ID must be set to 0.

3. Electrical Connection and Network Overview

Connect port 1 of the Smart Camera to 18…30 V DC. Connect pin 1 (wenglor standard cable: Brown) to the plus pole and pin 2 (wenglor standard cable: Blue) to the minus pole.

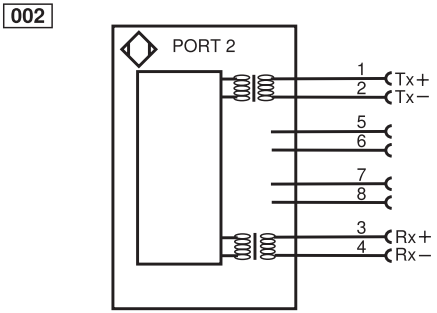


Connection Diagram, weQube Smart Camera, Port 1

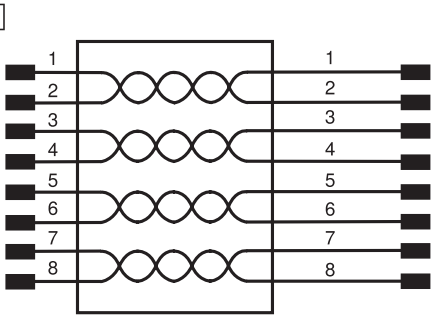


Matching wenglor Connection Equipment

- Connect port 2 of the Smart Camera for EtherNet/IP communication with a PLC – directly or via a switch.



Connection Diagram, weQube Smart Camera, Port 2



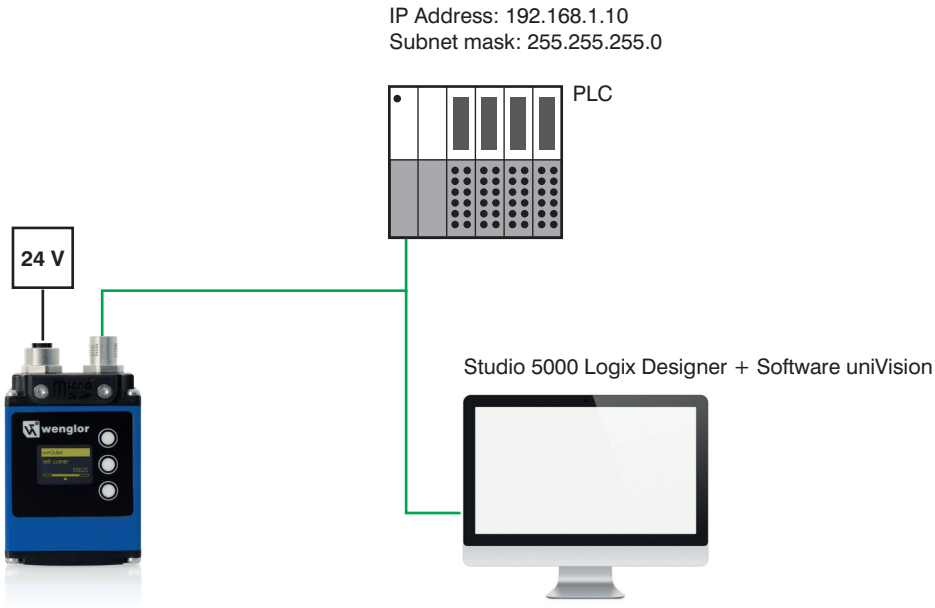
Matching wenglor Connection Equipment

LEDs for EtherNet/IP at the Smart Camera:

LED	Color	State	Meaning
MS (Module Status)	(Green)	On	Operation Ready
	(Green)	Flashing	Standby
	(Red)	On	Fatal Error
	(Red)	Flashing	Error
	(Off)	Off	Switched off
NS (Network Status)	(Green)	On	Connected
	(Green)	Flashing	No connection, but valid IP address
	(Red)	On	Network conflict: Another device in the network has the same network configuration.
	(Red)	Flashing	Connection Time-out
L/A	(Green)	On	Ethernet connection is available.
	(Green)	Flashing	Smart Camera sends or receives Ethernet frames.
	(Off)	Off	No Ethernet connection available.

NOTE!
Port 2 of the Smart Camera supports EtherNet/IP communication and further network functionality (e.g. Software uniVision for Windows, website, process data via TCP, UDP and FTP).

Example: The Smart Camera weQube, the PLC and a PC with the software Studio 5000 Logix Designer and uniVision are in the same network.



4. Input and Output Data

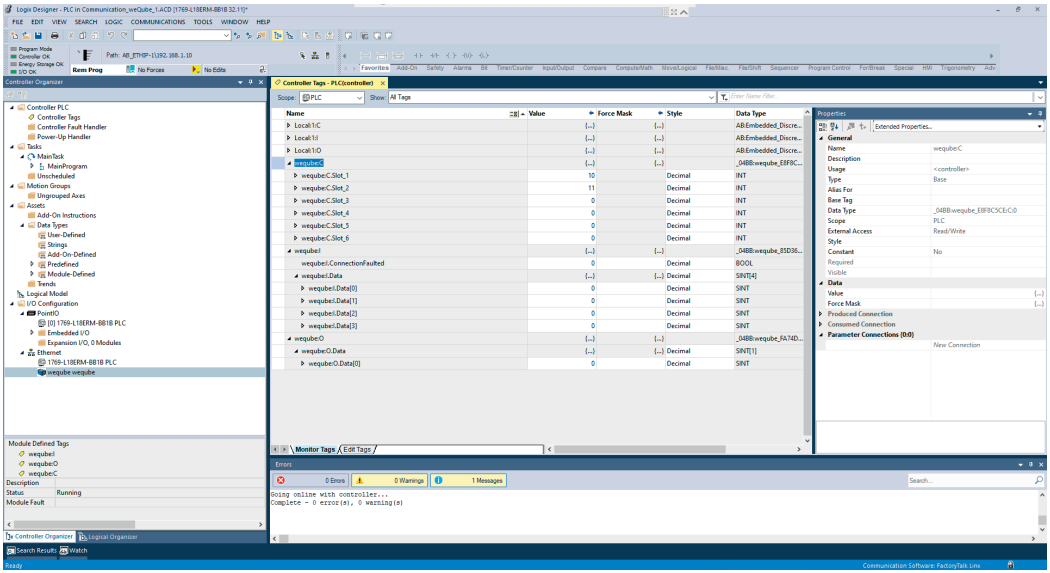
In the view of the PLC, the following input and output data are available for the Smart Camera:

- Slot 1 / weQube:O.Data[0] (fix): Project number (1 Byte Output of PLC)
- Slot 2 / weQube:I.Data[0-3] (fix): Status (4 Bytes Input of PLC)
- Slot 3 – 6 / weQube:I.Data or weQube:O.Data (flexible): User-defined process data (x Bytes Input or Output of PLC)

NOTE!
By default, slot 1 (weQube:O.Data[0]) and slot 2 (weQube:I.Data[0-3]) are always present. Slots 3 to 6 (weQube:I.Data or weQube:O.Data) are optional. The number of optional slots and the data types of such user-defined slots are adjustable.

The following example shows the default input and output configuration of the Smart Camera weQube with slot 1 (weQube:O.Data[0]) and slot 2 (weQube:I.Data[0-3]).

Example:



4.1 Status

The Smart Camera weQube sends a four-byte status information to the PLC. The status gives feedback as to whether the Smart Camera works correctly or is in an error state:

- Status 0: No error
- Status not 0: Error

In case of an error, the binary number indicates the reason of the respective error. The bit number starts with zero. Bits with value true give more information about the error.

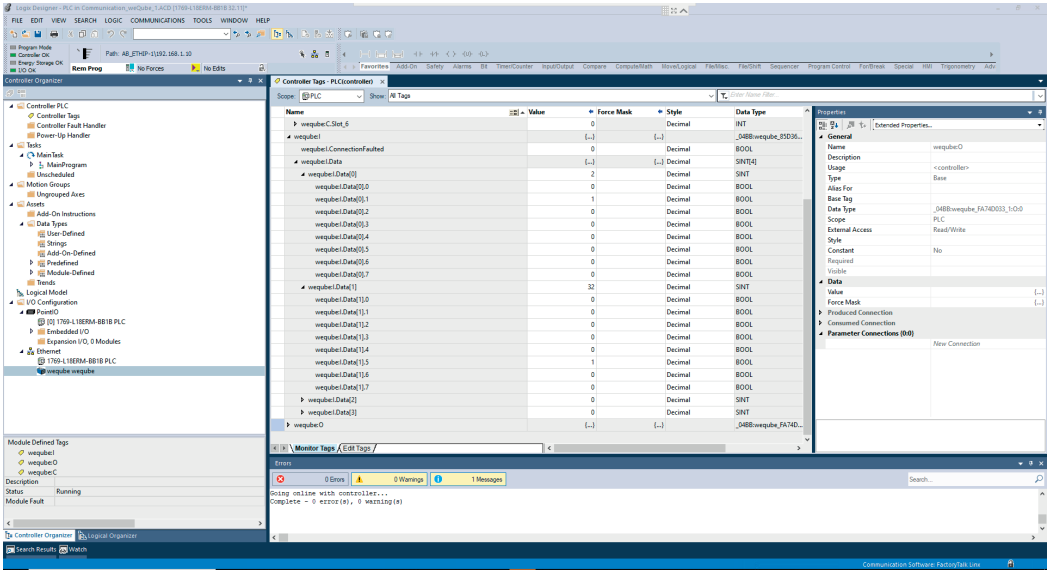
Bit	Section	Signal	Description
0	General	Information	Busy Is high while processing LIMA commands (e.g. because of loading a project or changing any project parameter).
1		Warning	There is at least one bit set, level = Warning
2		Critical Error	There is at least one bit set, level = Critical Error
3		Fatal Error	There is at least one bit set, level = Fatal Error
6	Peripheral	TCP/IP	There is an error concerning the TCP/IP socket
7		UDP	There is an error concerning the UDP socket
8		Industrial Ethernet	There is an error concerning industrial ethernet
12		UART	There is an error concerning the UART device
13		FTP	There is an error concerning the FTP interface.
14	Memory	Flash	There is an error concerning the flash access
15		RAM	There is an error concerning the RAM access
16		SD-Card	There is an error concerning the SD card access
17		File access	There is an error concerning a general file access.
18		Compatibility	There is an error concerning the version of the loaded project
24	Image Processing	Sequencing	There is an error concerning IData vision engine
25		Processing	There is an error concerning a vision module.
26		Trigger	There is an error concerning HW trigger

NOTE!
More details about errors and possible solutions are available in the uniVision software manual.

Example:
The status with the binary number 10 0000 0000 0010 shows an error at bit 1 and bit 13. Consequently, there is a warning that indicates a problem with the FTP interface. An example may be that the Smart Camera is configured to save data on a FTP server, but the FTP server is not available in the network.

Bit	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Binary number	1	0	0	0	0	0	0	0	0	0	0	0	1	0

The following screen shows the status bits of the Smart Camera weQube in Studio 5000 Logix Designer in case of the described FTP error.



4.2 Commands

Commands (e.g. trigger commands) are sent from the PLC to the Smart Camera. The Smart Camera weQube supports the following commands:

- Trigger
- Load project

It is not allowed to send several commands (e.g. trigger and project load commands) at the same time! Before sending the next command, it is necessary to wait until the processing of the last command has finished completely.

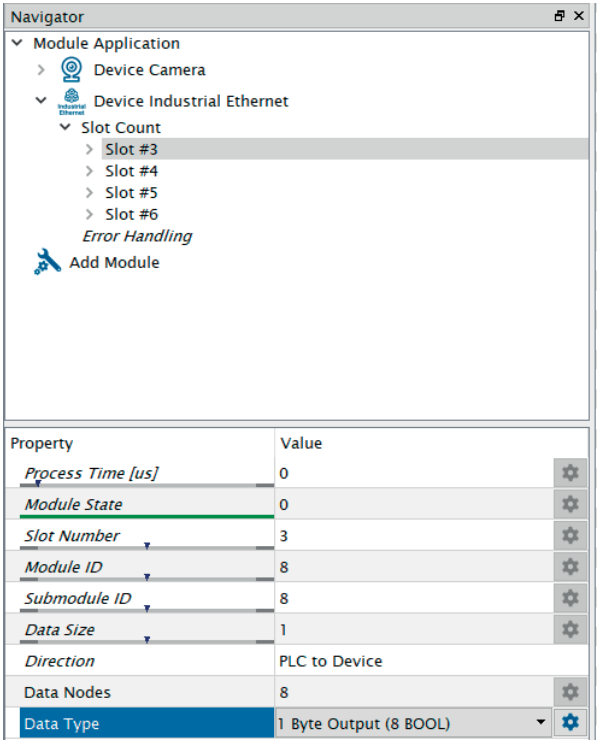
NOTE!
When the PLC sends a command to the Smart Camera, the Smart Camera captures an image or loads the project. Commands are executed immediately in contrast to process data, which is only sent or received by the Smart Camera in case of an evaluation that was started by a trigger signal.

4.2.1 Trigger Command

When the PLC sends a trigger command to the Smart Camera, the Smart Camera captures and evaluates an image and sends the results.

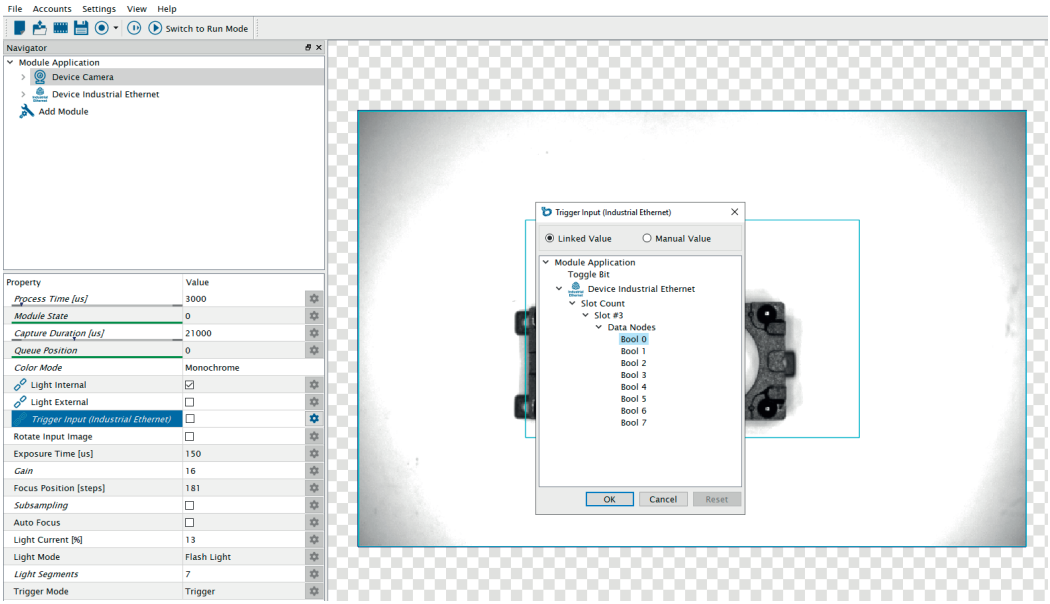
The following steps are necessary to set up a trigger command via EtherNet/IP:
1. Connect to the Smart Camera via the software uniVision for Windows.
2. Add Device Industrial Ethernet to the project.
3. Set Slot Count to define the number of flexible slots (At least one flexible slot is required for the trigger command).
4. Configure one of the flexible slots as 1 Byte Output (8 BOOL)

In the following example, the trigger command via EtherNet/IP is sent at slot 3.



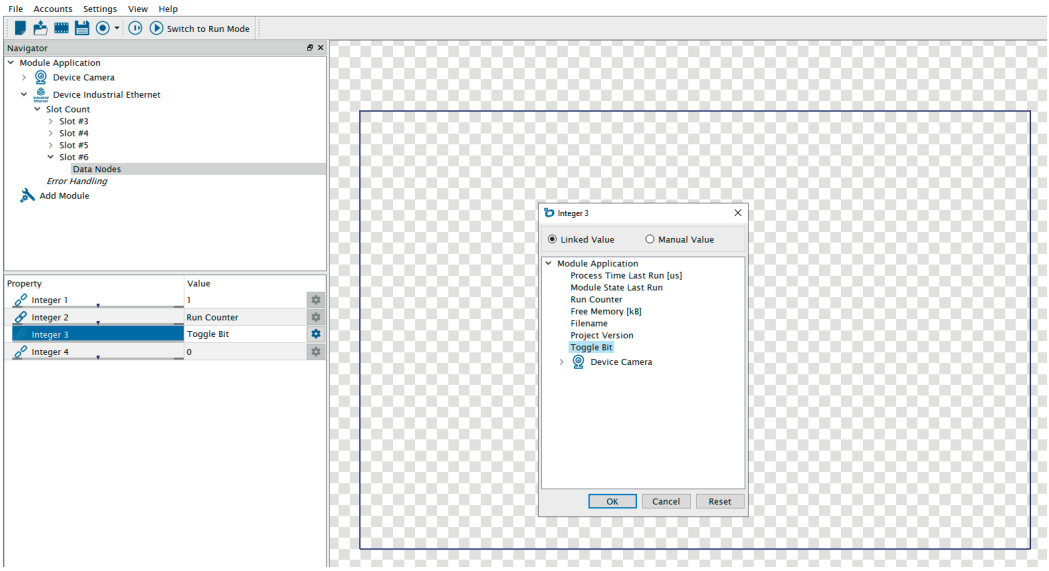
5. Select Device Camera and link one of the bools of slot 3 to Trigger Input (Industrial Ethernet). In the example, the PLC sends the trigger command at Bool 0 of slot 3.

NOTE!
For triggering via EtherNet/IP, the Trigger Mode of Device Camera must be set to Trigger. Trigger Input (Industrial Ethernet) is only visible in the extended view of the uniVision software.



6. Use the last slot in order to verify that all new results of the image evaluation are available on the PLC. For example, configure slot 6 as “16 Byte Input (4 DINT)” and link the toggle bit and the run counter:

- Integer 1: Fix project number
- Integer 2: Run counter
- Integer 3: Toggle bit



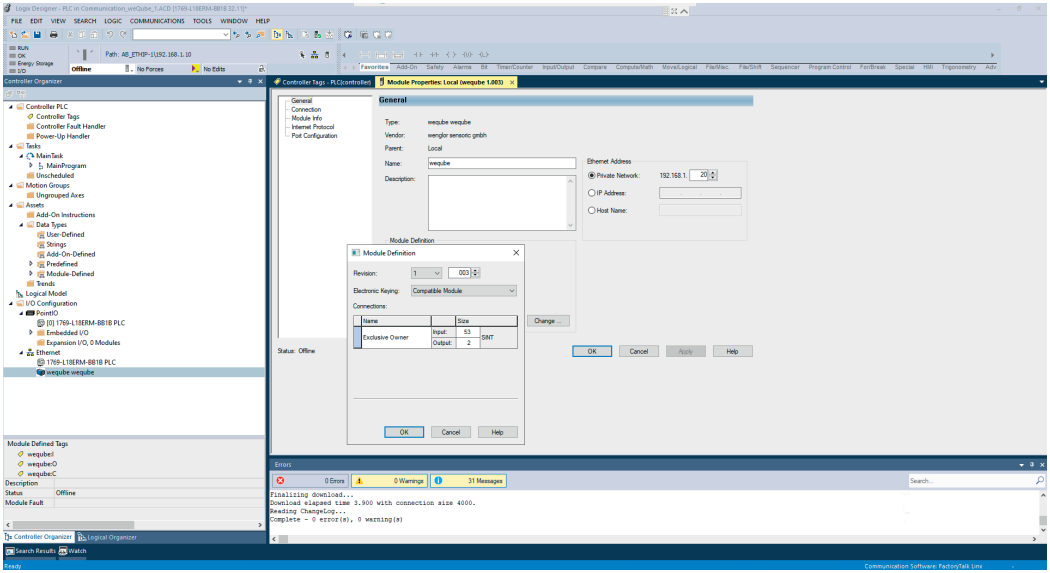
NOTE!
Save the project, set it as startup project and reboot the Smart Camera to apply the settings.

7. Open the software Studio 5000 Logix Designer and adjust the number of input and output addresses of the Smart Camera according to the configuration in the uniVision project.

NOTE!
A detailed description of how to set up the input and output addresses is shown in chapter "7.3 Configure Input and Output Data" on page 40.

The example with 53 bytes input (4 + 1 + 32 + 16) and 2 bytes output (1 + 1) works for the following slot configuration:

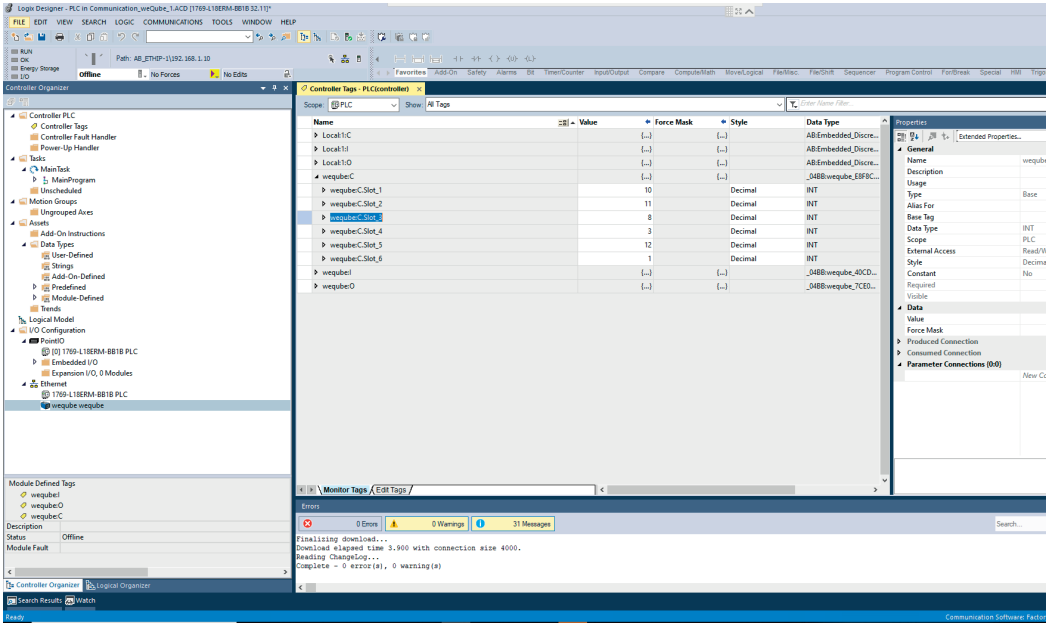
- Slot 1 (fix): 1 Byte Output (Project number)
- Slot 2 (fix): 4 Byte Input (Status)
- Slot 3: 1 Byte Output (8 BOOL)
- Slot 4: 1 Byte Input (8 BOOL)
- Slot 5: 32 Byte Input (2 CHAR)
- Slot 6: 16 Byte Input (4 DINT)



8. Set the Module IDs in weqube:C according to the configuration in the uniVision project.

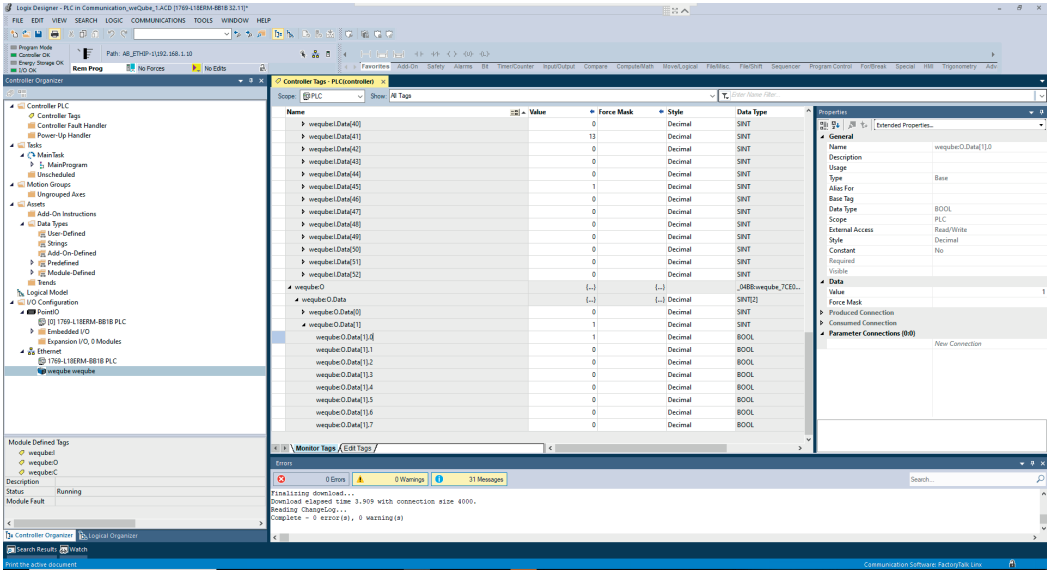
NOTE!
A detailed description of all Module IDs is shown in chapter "7.3 Configure Input and Output Data" on page 40.

In the example, the following Module IDs must be used:
- Slot 1 (fix): Module ID 10
- Slot 2 (fix): Module ID 11
- Slot 3: Module ID 8
- Slot 4: Module ID 3
- Slot 5: Module ID 12
- Slot 6: Module ID 1



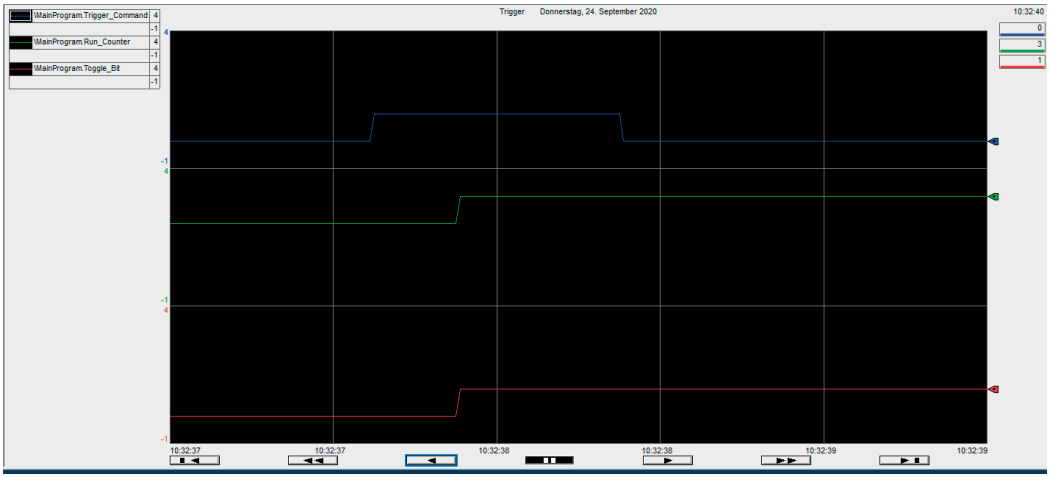
9. Download the configuration of the software Studio 5000 Logix Designer to the PLC and go online.

10. Send the value TRUE to the correct address to send a trigger command to the Smart Camera. With every change from FALSE to TRUE for the trigger command bit, the Smart Camera captures and evaluates an image.
    In the example, the trigger signal is sent on weqube:O.Data[1].0. The result of the run counter can be seen on weqube:I.Data[41-44] and the result of the toggle bit is shown on weqube:I.Data[45].0.



NOTE!

- After capturing and evaluating the image, the Smart Camera sends results in the form of process data (also via EtherNet/IP if configured accordingly).
- The processing of the trigger signal and the evaluation of the image is completed when the toggle bit has changed and the run counter has increased by one.
- It is not allowed to send several commands at the same time (e.g. trigger and load project commands).
- After a trigger command has been sent from the PLC to the Smart Camera, wait until the results are available on the PLC before sending the next command.



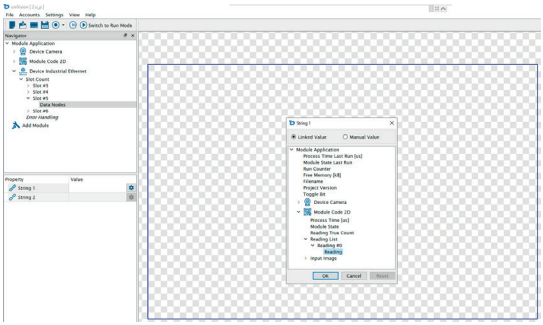
4.2.2 Load Project Command

The load project command allows loading another project onto the Smart Camera. Up to 255 different projects can be loaded via EtherNet/IP.

The following steps are necessary to set up a load project command via EtherNet/IP:
1. Open the software uniVision for Windows and connect to the Smart Camera weQube.
2. Create uniVision projects and save them with a number at the beginning of the filename.

NOTE!
In order to load projects via EtherNet/IP, all projects must be saved in the following format: “xxx_testproject.u_p” (x = any integer from 0 to 9). For example “001_MyProject.u_p”. Project numbers can be set between 1 and 255 (0 is ignored – default value). Use unique numbers for every uniVision project file. The number of slots and the slot configuration must be identical in all uniVision projects in the Smart Camera in order for the project change to be possible from the PLC.

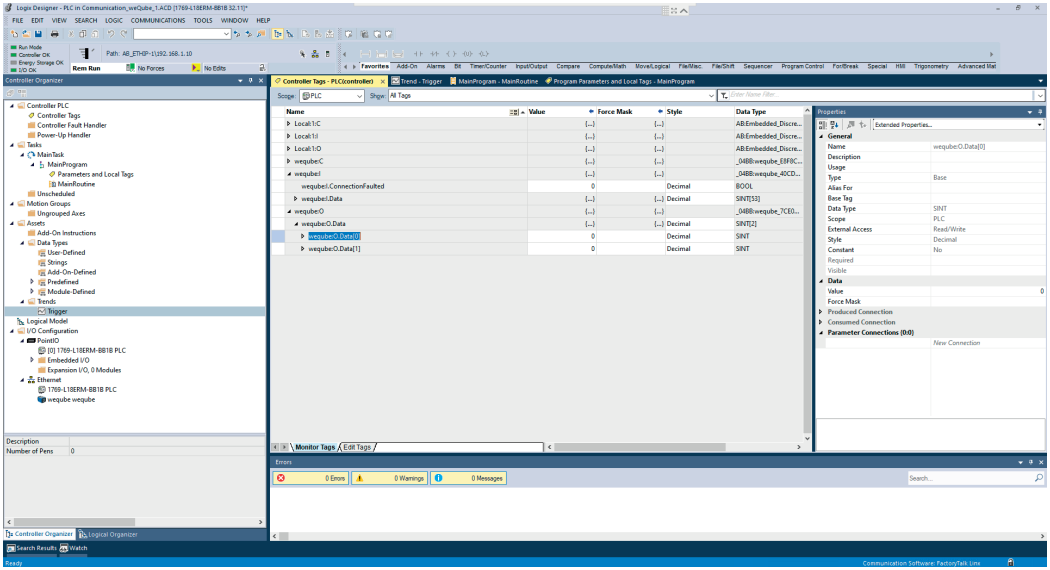
3. Use the last slot in order to send the project number as a fix result from the Smart Camera to the PLC. This value can be used to verify that the project has finished loading.



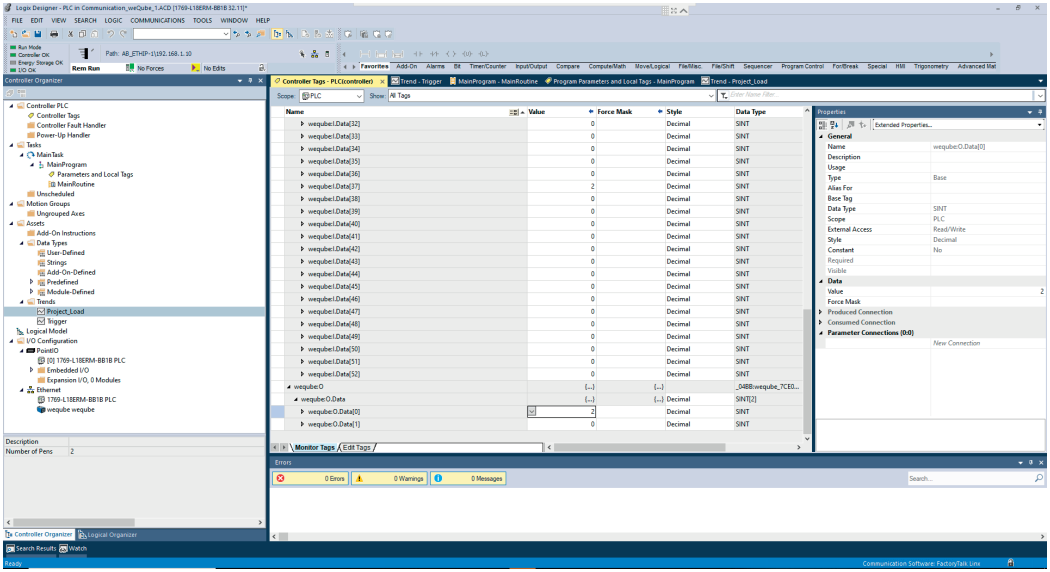
NOTE!
Save the projects, set one of the projects as startup project and reboot the Smart Camera to apply the settings.

4. Open the software Studio 5000 Logix Designer.

5. Slot 1 / weQube:O.Data[0] (fix) of the Smart Camera is pre-configured for loading uniVision projects.



6. Send the number defined in the filename of the uniVision project from the PLC to the Smart Camera in order to load the project. With every change of the project number sent by the PLC to the Smart Camera, the Smart Camera loads the project (only if the uniVision project is available and if the project number is different to the currently loaded project).
   In the example, the project number 2 is sent at weqube:O.Data[0]. After the project loading has finished, the weQube sends the current project number back at weqube:I.Data[37-40].



NOTE!

- After loading the project, the Smart Camera initializes all results (e.g. run counter is reset to 0).
- The project has finished loading when the result of the project number is available on the PLC.
- It is not allowed to send several commands at the same time (e.g. trigger and load project commands).
- After a load project command is sent from the PLC to the Smart Camera, wait until the result of the project number is available on the PLC before sending the next command.

NOTE!

After starting the Smart Camera weQube, the startup project defined in the global properties is loaded. It is possible to send a command to load another project from the PLC to the Smart Camera before the booting process is finished, but it is necessary to wait until the Smart Camera responds with the correct project number before sending the first trigger command.

4.3 User-Defined Process Data

All other EtherNet/IP values in the uniVision project are process data. Process data is sent from the device to the PLC and vice versa. Details are available in the Smart Camera settings (see section “5.2 Device Industrial Ethernet”, page 24).

NOTE!

Compared to commands and status data that are updated continuously, process data is only evaluated and sent when an image is executed because of a trigger signal.

5. Smart Camera Settings

For EtherNet/IP communication, the following steps are necessary at the Smart Camera.

NOTE!

- The Smart Camera weQube supports EtherNet/IP functionality starting with the Smart Camera firmware version 2.3.0 and the uniVision software version 2.3.0.
- Not all Smart Cameras support EtherNet/IP communication. Check the technical data on the wenglor website for details about every Smart Camera version.

5.1 Set Up uniVision Projects

The following steps are necessary in order to create a communication between the Smart Camera and the PLC:

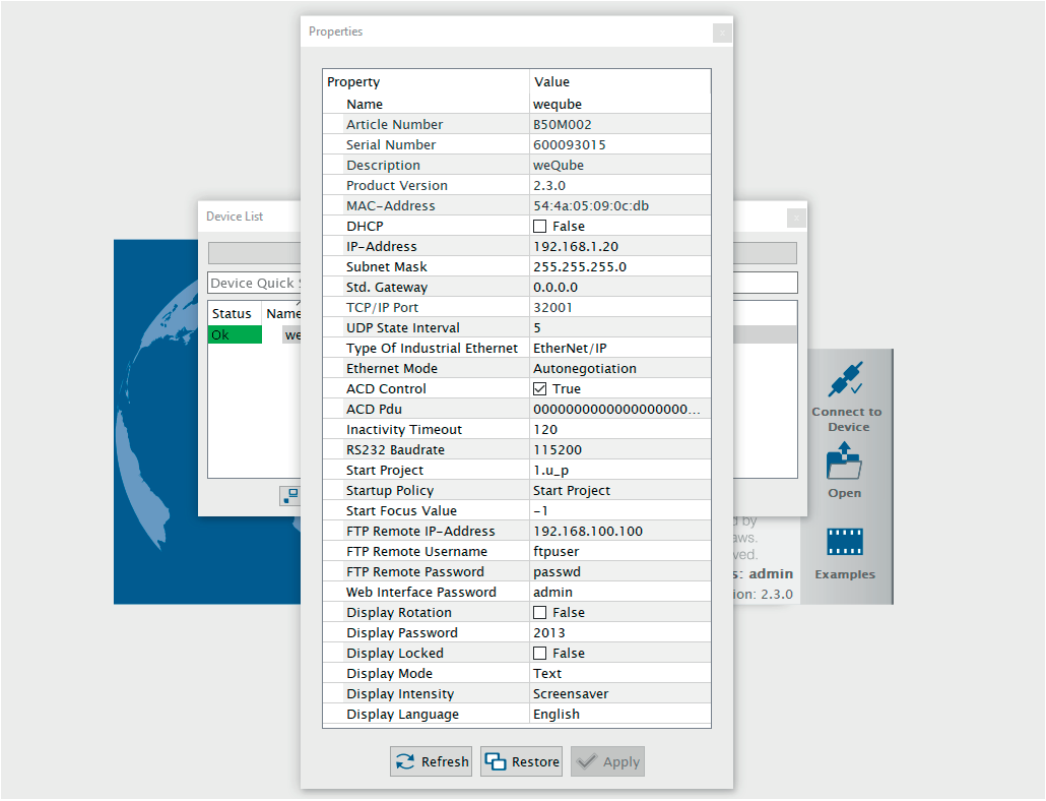
1. Install and open the software uniVision for Windows.
2. Set up the network configuration and the device name of the Smart Camera via the software uniVision.

NOTE!

It is recommended to directly allocate the network configuration and device name to the Smart Camera that is to be used in the EtherNet/IP network later.

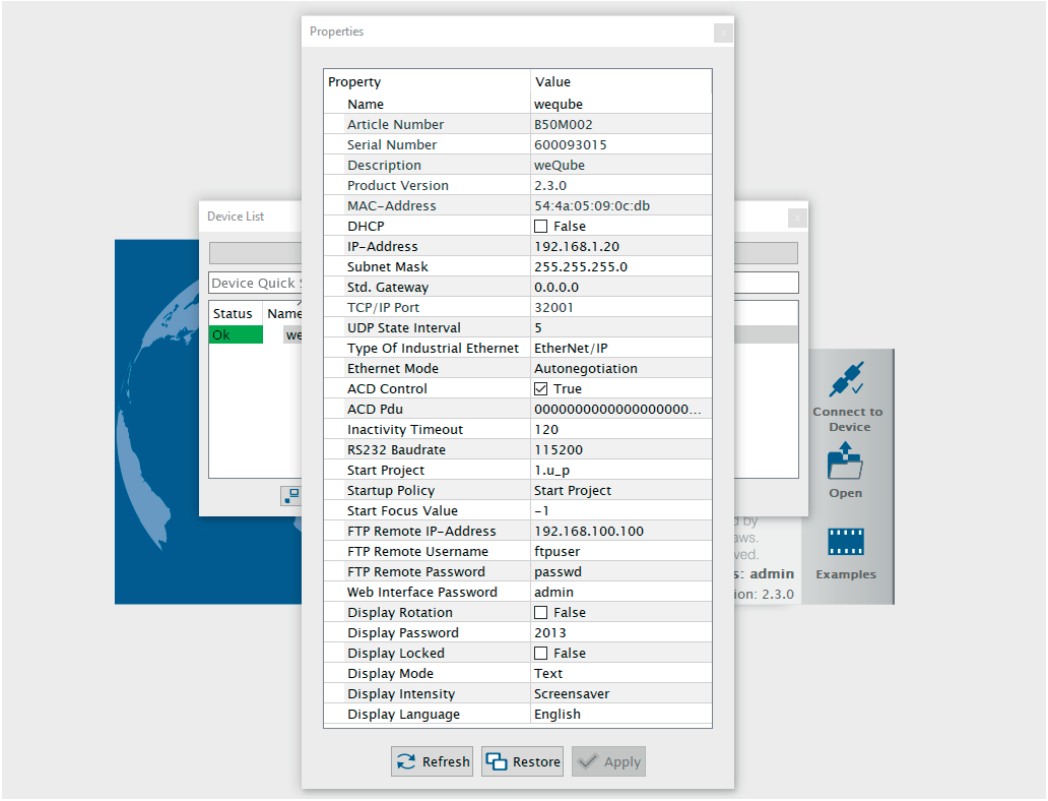
NOTE!

It is possible to use a static network configuration or to activate DHCP at the Smart Camera. In case of activated DHCP, a DHCP server (e.g. BOOTP) is needed in the network so that the Smart Camera gets a valid network configuration (see section "6. EtherNet/IP Network Configuration of the Smart Camera" on page 30). If no DHCP server is available, the Smart Camera will not boot completely. The DHCP setting can be disabled temporarily by pressing the key in the middle of the OLED display on the Smart Camera during start-up.



3. Connect to the Smart Camera.
4. Edit and save uniVision projects on the Smart Camera. All projects must contain Device Industrial Ethernet (see section “5.2 Device Industrial Ethernet”, page 24).

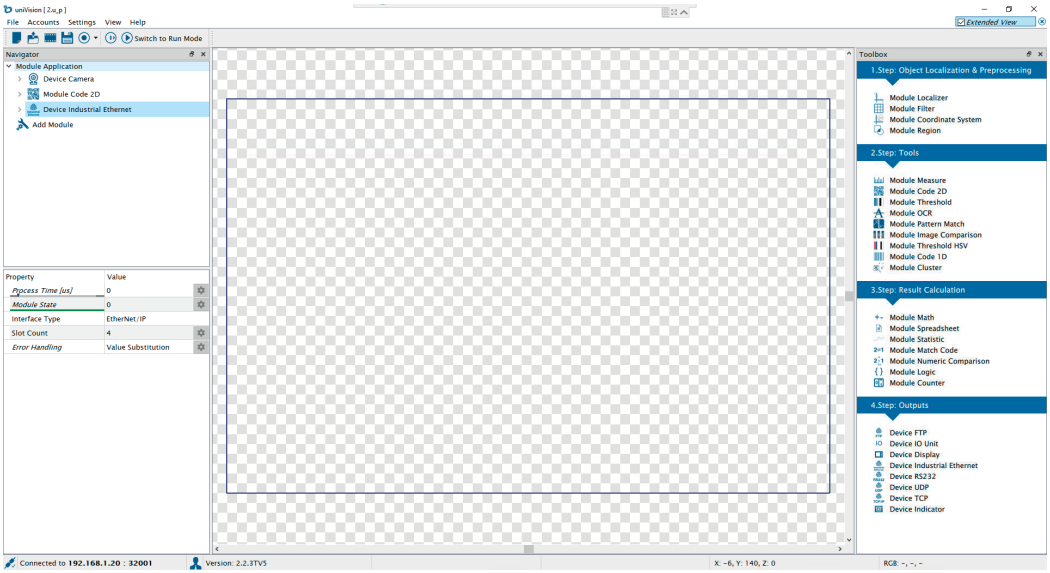
5. Open the Properties of the Smart Camera in the Device List to set up the startup behavior. It is necessary to select a valid startup project with a suitable EtherNet/IP configuration.
   It is also necessary to set “Type of Industrial Ethernet” to “EtherNet/IP” for EtherNet/IP communication (Default: Profinet). Furthermore, you can select if the Address Conflict Detection for EtherNet/IP should be activated or deactivated. Reboot the Smart Camera to apply the settings.



NOTE!
Details about all listed steps are explained in the uniVision software manual.

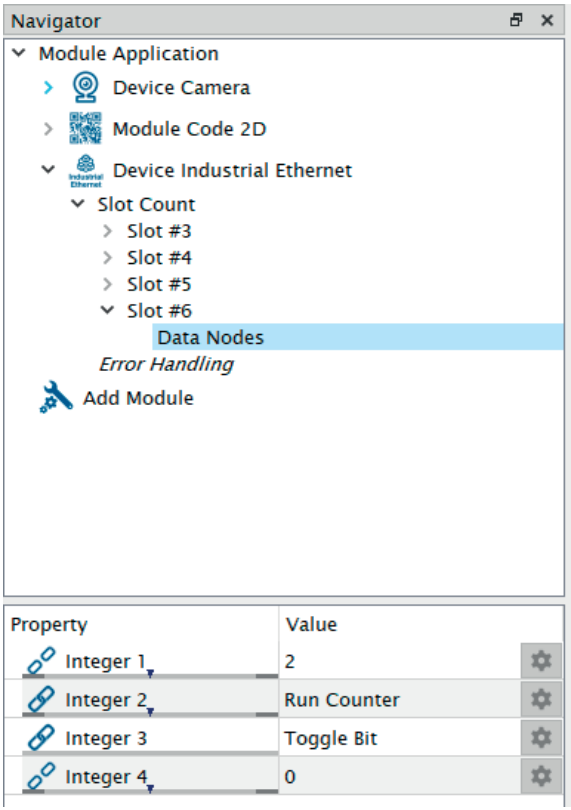
5.2 Device Industrial Ethernet

Add Device Industrial Ethernet to the uniVision projects from the toolbox to configure the flexible input and output data. The Smart Camera supports up to four slots to send or receive process data. With one of the flexible slots, it is also possible to send the trigger command to the Smart Camera (see section “4.2.1 Trigger Command”, page 11).



NOTE!

- Compared to commands and status data that are updated continuously, process data is only evaluated and sent when an image is evaluated because of a trigger signal.
- Only within one slot is the process data sent and received consistently in one EtherNet/IP cycle. The process data from different slots of the Smart Camera to the PLC may be updated in different EtherNet/IP cycles. Use the last slot to make sure that all results are refreshed, e.g. by linking the run counter or the toggle bit to a value from the last slot.
- Furthermore, it is recommended to also send the project number as fixed value in the last slot in order to verify on the PLC side that the project loading process is finished.
- After changing the number of slots or the slot configuration, the Smart Camera must be restarted with a suitable start-up behavior (e.g. fixed start-up project) in order for the settings to be applied correctly.
- The number of slots and the slot configuration must be identical in all uniVision projects in the Smart Camera in order for the project change to be possible from the PLC.



Property	Description
Process Time [us]	Time in μs for processing the module.
Module State	Indicates the status of the module: • 0: No error • Value different to 0: Error (Details about the error code are available in the uniVision software manual)
Interface Type	Indicates the interface type.
Slot Count	Number of flexible slots (Slots 3 – 6). **NOTE!** • By default, the number of flexible slots is set to 0. • Fours flexible slots can be configured at a maximum.
Error handling	If any process data is in error state, it is substituted by a user-defined replacement value (see section “5.2.2 Error Handling”, page 29).

5.2.1 Slots

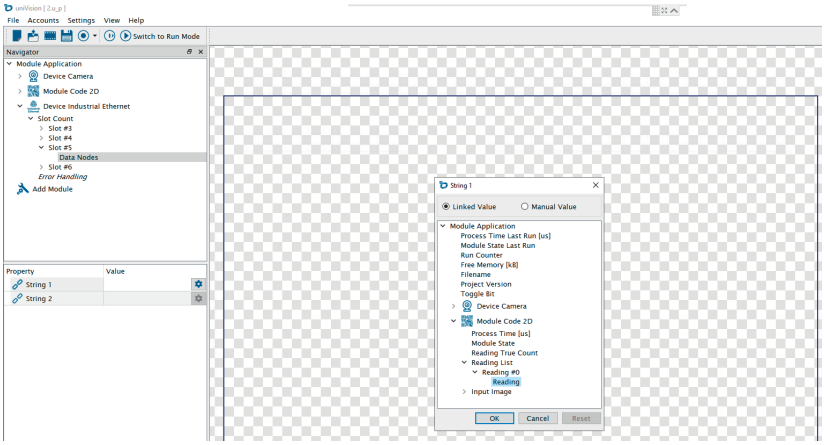
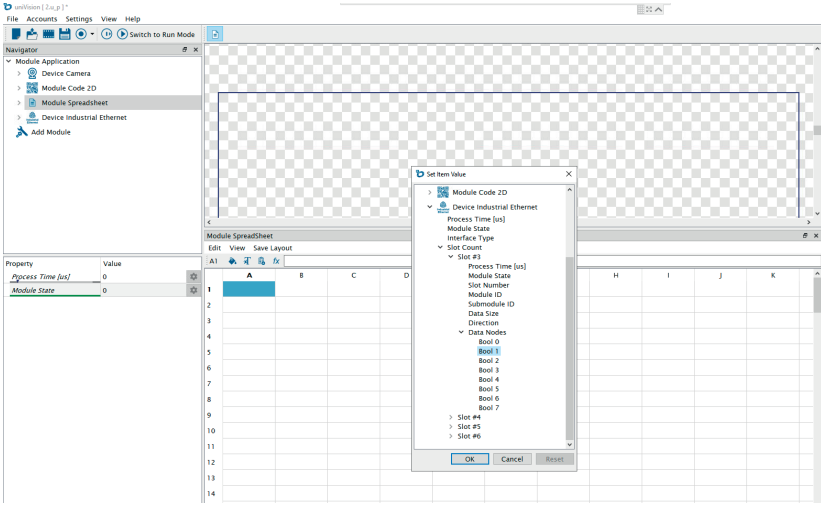
Set up the configuration for every EtherNet/IP slot.

NOTE!
Activate the extended view in the uniVision software in order to be able to see all values (especially the module ID and direction).

Property	Description
Process Time [us]	Time in μs for processing the module.
Module State	Indicates the status of the module: • 0: No error • Value different to 0: Error (Details about the error code are available in the uniVision software manual)
Slot Number	Indicates the slot number.
Module ID	Indicates the Module ID.
Submodule ID	Indicates the Submodule ID.
Data Size	Indicates the data size in bytes.
Direction	Indicates the direction in which data is sent: • Device to PLC: Values are sent from the Smart Camera to the PLC. • PLC to Device: Values are sent from the PLC to the Smart Camera.
Data Nodes	Indicates the number of data nodes.
Data Type	Select the data type of the slot. The Smart Camera supports the following data types: • 16 Byte Input (4 DINT) • 16 Byte Input (4 REAL) • 1 Byte Input (8 BOOL) • 128 Byte Input (2 CHAR) • 16 Byte Output (4 DINT) • 16 Byte Output (4 REAL) • 1 Byte Output (8 BOOL) • 128 Byte Output (2 CHAR) • 32 Byte Input (2 CHAR) • 64 Byte Input (2 CHAR) • 256 Byte Input (2 CHAR) • 32 Byte Output (2 CHAR) • 64 Byte Output (2 CHAR) • 256 Byte Output (2 CHAR)  **NOTE!** • Use BOOL to send or receive true/false results (e.g. toggle bit). • Use REAL to send or receive numbers with positions after decimal point (e.g. x value of a found point). • Use DINT to send or receive numbers without positions after decimal point (e.g. pixel count value of Module Threshold). • Use CHAR to send or receive text information (e.g. code result).

Property	Description
Data Type	Linking results to the different data types works as follows: • BOOL (output) – Link BOOL result: Returns true or false depending on value of bool – Link DINT or REAL result: Returns true if the current value is within thresholds (between the minimum and maximum thresholds) and returns false if the current value is out of tolerance (lower than the minimum or higher than the maximum thresholds) – Link CHAR: Returns true if the text is not empty and returns false if the text is empty. • DINT (output) – Link BOOL result: Returns 0 for bool value false and 1 for bool value true. – Link DINT: Returns current DINT value – Link REAL: Returns a number without decimal places (no rounding!) – Link CHAR: Returns the number of digits of the text • REAL (output) – Link BOOL result: Returns 0 for bool value false and 1 for bool value true. – Link DINT or REAL: Returns a number with decimal places – Link CHAR: Returns the number of digits of the text • CHAR (output) – Link BOOL result: Returns false for bool value false and true for bool value true – Link DINT or REAL: Returns the number – Link CHAR: Returns the text

In the project tree, data nodes appear below the slot.

Double, Integer, BOOL or String (depending on the data type of the slot)	Values (Results) from the device to the PLC can be set to a certain value manually or can be linked with any result of the project (e.g. with the reading result of Module Code 2D).  Values from the PLC to the device are shown as uniVision input values. **NOTE!** • Process data from the PLC to the Smart Camera is only received when an image is evaluated in the Smart Camera because of a trigger signal. • Process data from the PLC to the Smart Camera is linked as input in other modules (e.g. in the Module Spreadsheet). 

5.2.2 Error Handling

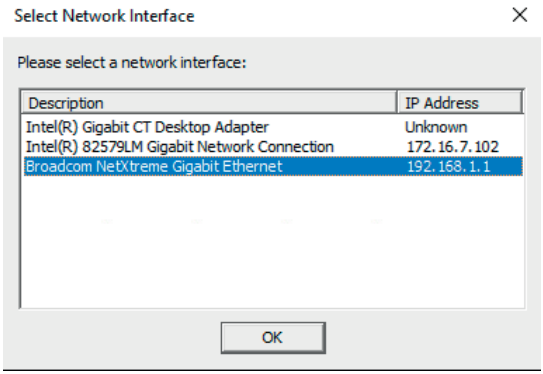
If any process data is in error state, the substitution value can be selected for every data type.

Property	Description
Substitute Bool Types by	If a bool type used in Device Industrial Ethernet is in error state, it is replaced by low or high (Default: low).
Substitute INT Types by	If an INT type used in Device Industrial Ethernet is in error state, it is replaced by any user-defined INT value (Default: 0).
Substitute DOUBLE Types by	If a DOUBLE type used in Device Industrial Ethernet is in error state, it is replaced by any user defined DOUBLE value (Default: 0.0000)
Substitute STRING Types by	If a STRING type used in Device Industrial Ethernet is in error state, it is replaced by any user-defined STRING value (Default: Error).

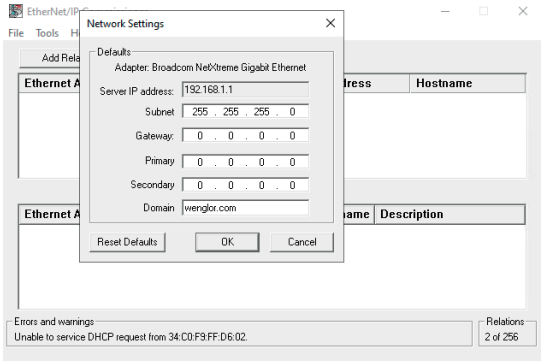
6. EtherNet/IP Network Configuration of the Smart Camera

The network settings of the Smart Camera can be set manually or can be allocated via a DHCP server.

In case of DHCP, use e.g. the software BOOTP to allocate the network settings to the Smart Camera:
1. Open software BOOTP.
2. Select the correct LAN adapter and click on OK.



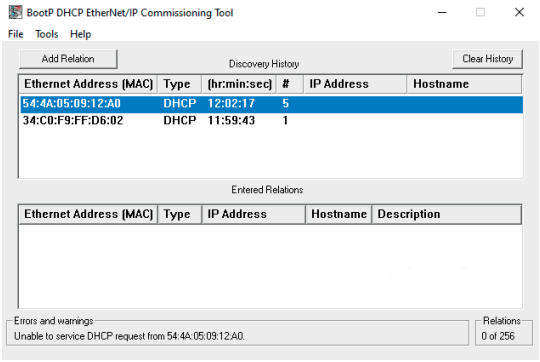
Click on “Tools” → “Network Settings” to enter the network settings of the PC.



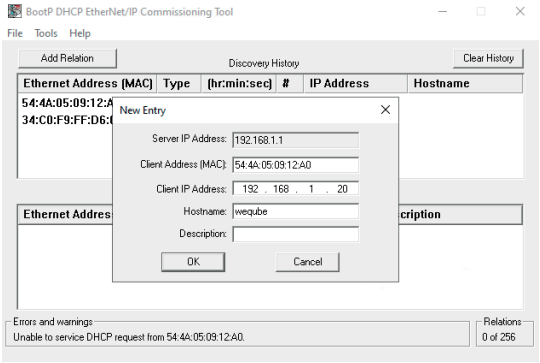
All devices with activated DHCP settings connected to the LAN adapter are listed.

3. Select the Smart Camera weQube and click on “Add Relation”.

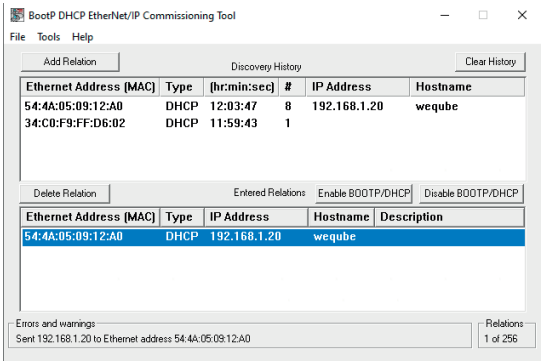
NOTE!
The MAC address is available on the housing of the Smart Camera.



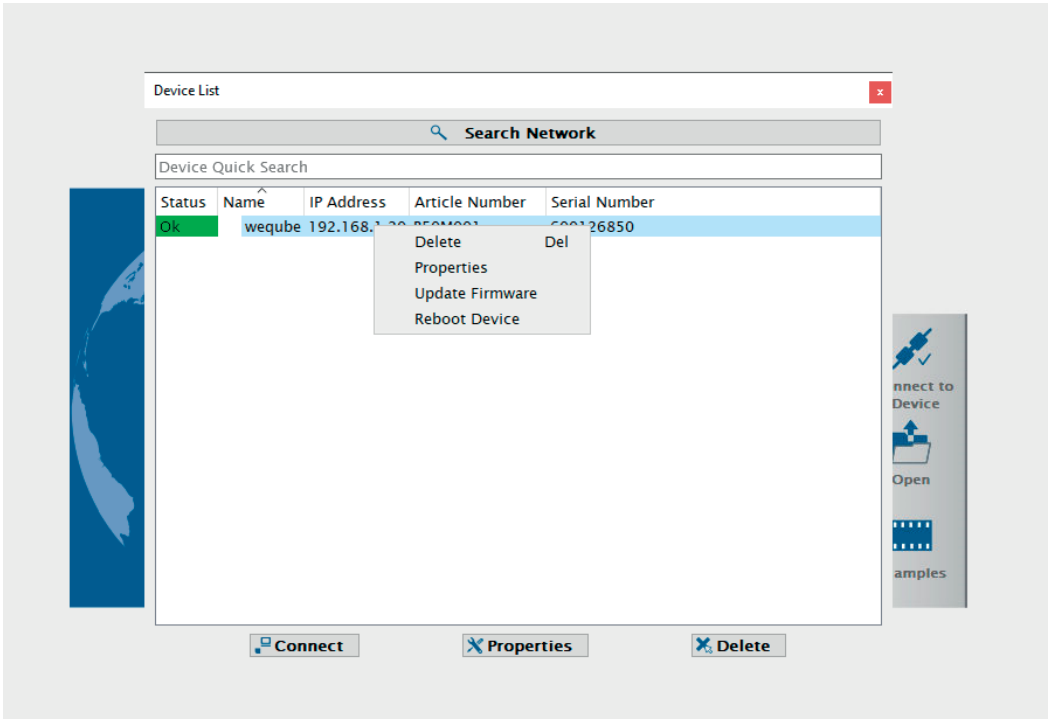
4. Enter IP address and hostname of the Smart Camera and click on OK.



5. In order to keep the network settings for the next start-up of the Smart Camera, select weQube and click on “Disable BOOTP/DHCP”.



6. Reboot the Smart Camera to apply the changed network settings (via Software uniVision → Device List).



7. PLC Settings at Allen-Bradley PLCs

The following settings are necessary on the Rockwell PLC.

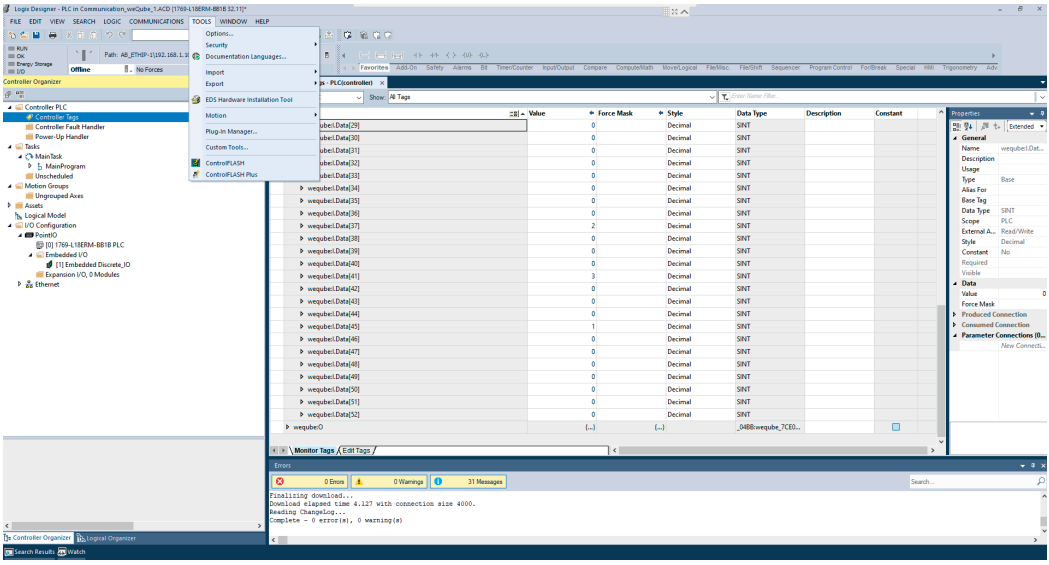
NOTE!
If possible, use the EDS file to integrate the Smart Camera. In case of some old Rockwell PLCs, EDS files are not supported. Consequently the Smart Camera must be integrated as generic device (see section "7.5 Integrate Smart Camera without EDS file" on page 45).

7.1 EDS File

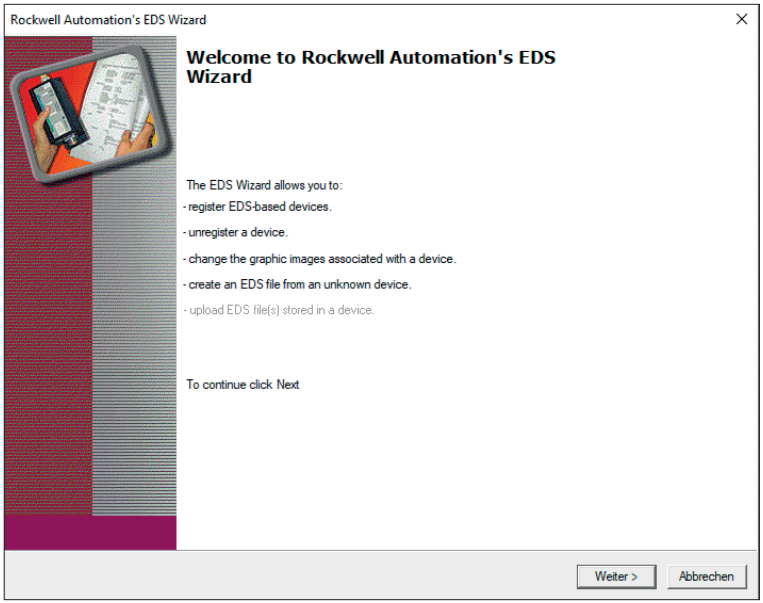
The EDS file is available on the wenglor website in the Download section of the Smart Camera. Download the EDS file, unzip the file and install it on the PLC.

NOTE!
After downloading the zip file, please unzip the file before installing it on the PLC.

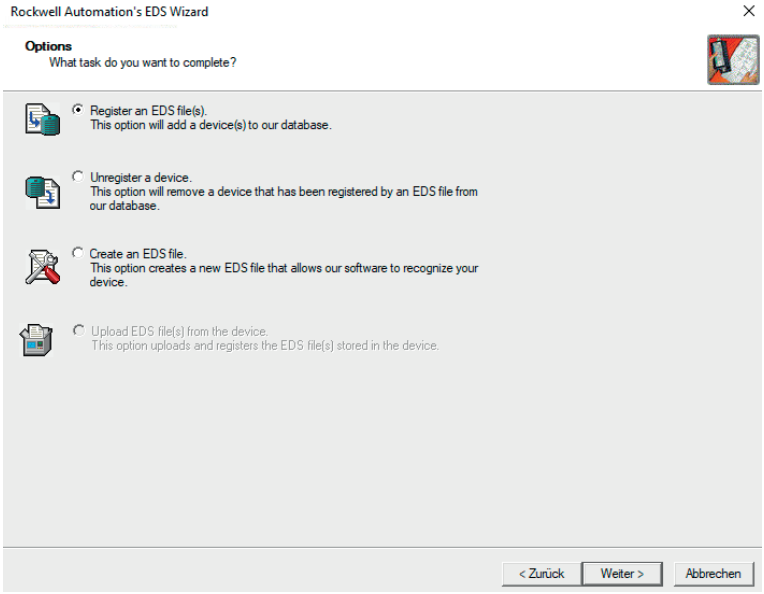
In the software Studio 5000 Logix Designer V32, the EDS file is added via “TOOLS” → “EDS Hardware Installation Tool”.



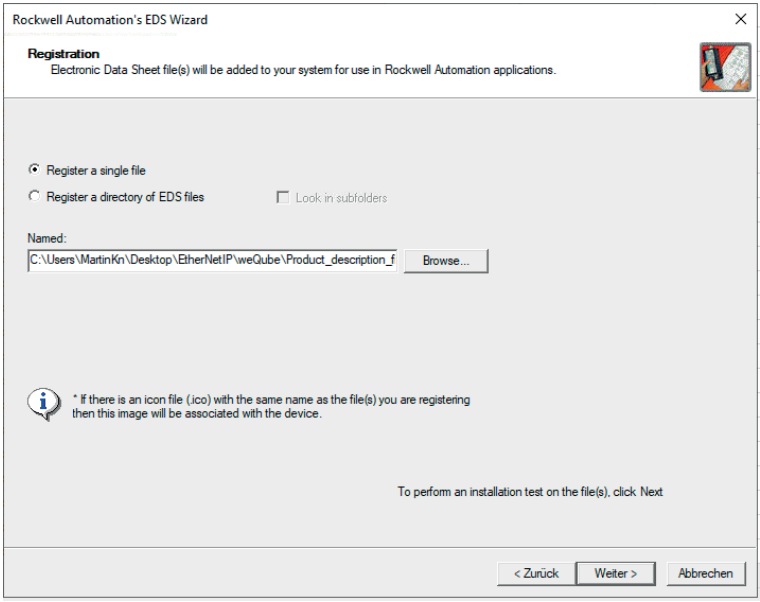
The EDS wizard starts.



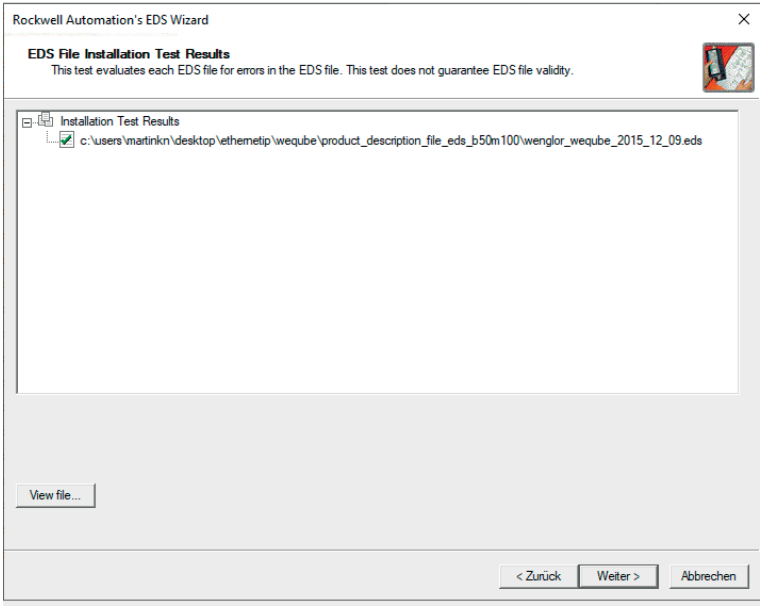
Select “Register an EDS file(s)”.



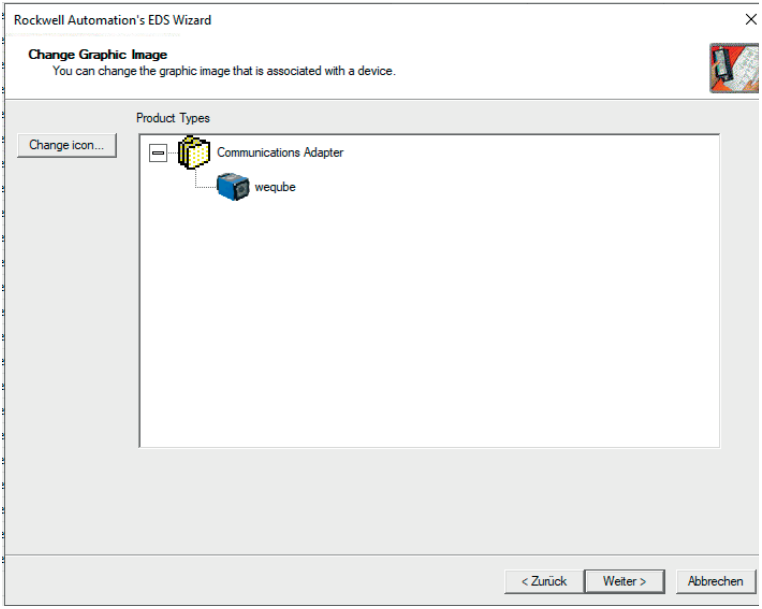
Select the path of the EDS file.



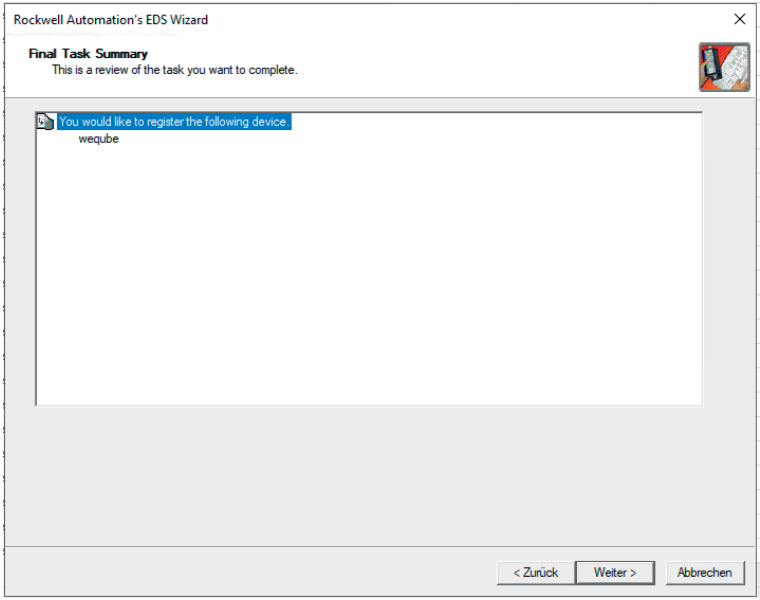
Add the EDS file to the project. It is also possible to view the file.



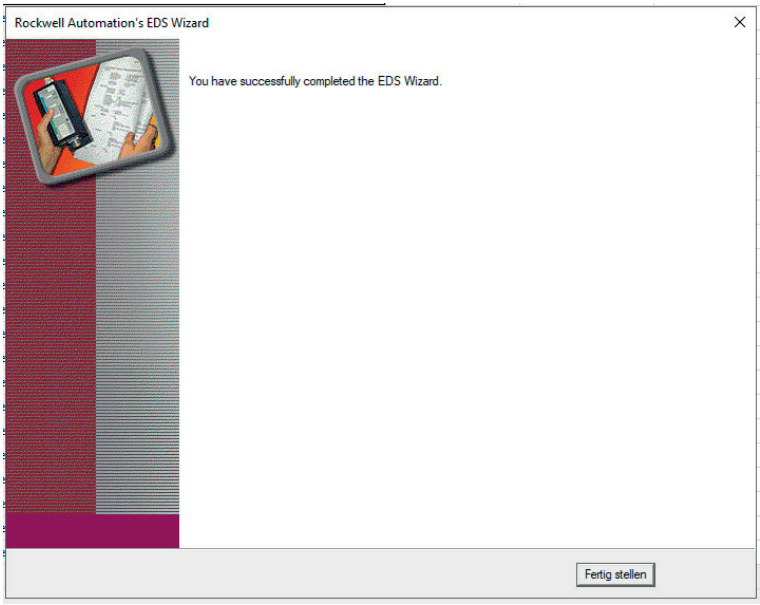
The image associated with the device is shown.



Add the selected device.

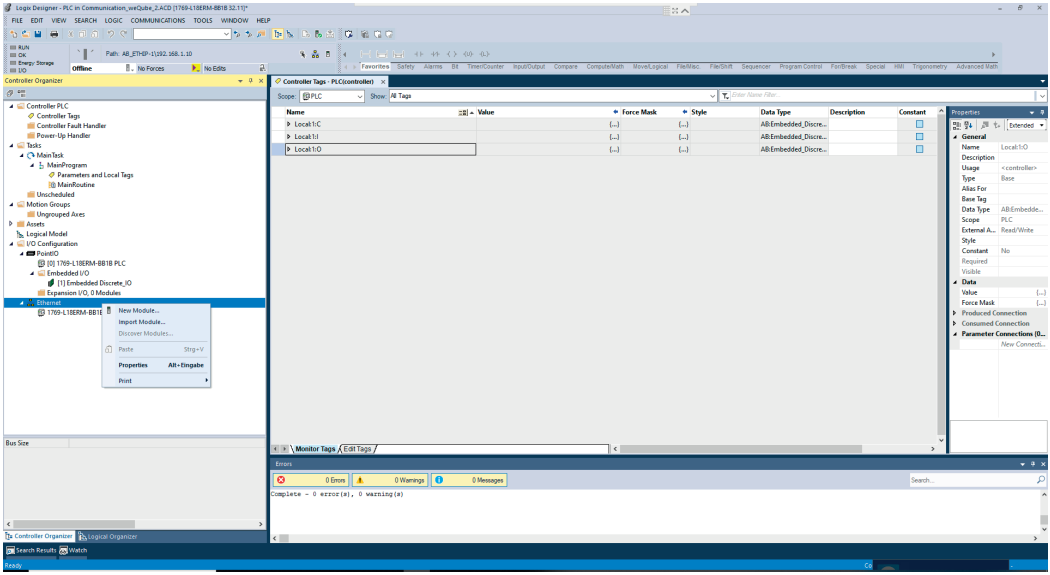


The installation of the EDS file is finished.

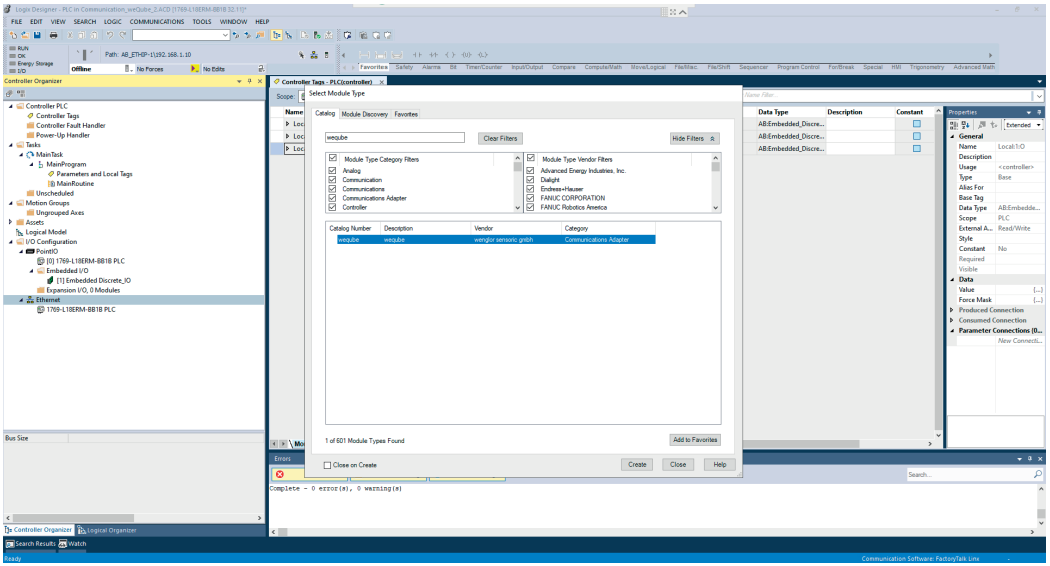


7.2 Add Smart Camera to PLC Network

Open the context menu at “Ethernet” with a right click and select “New Module…” to add the Smart Camera to the PLC network.

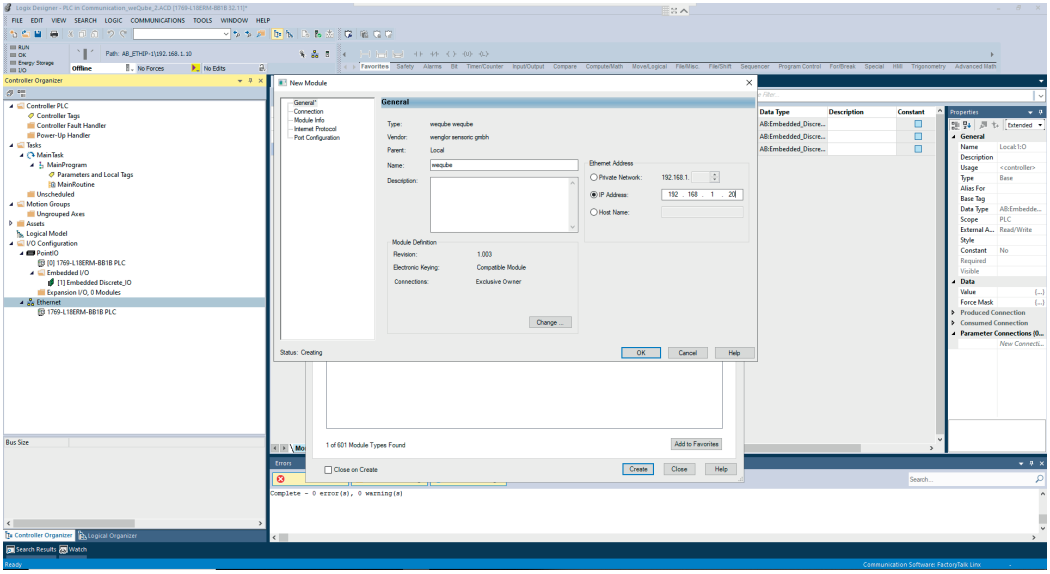


Then search for weqube in the catalog. Select weqube and click on “Create”.



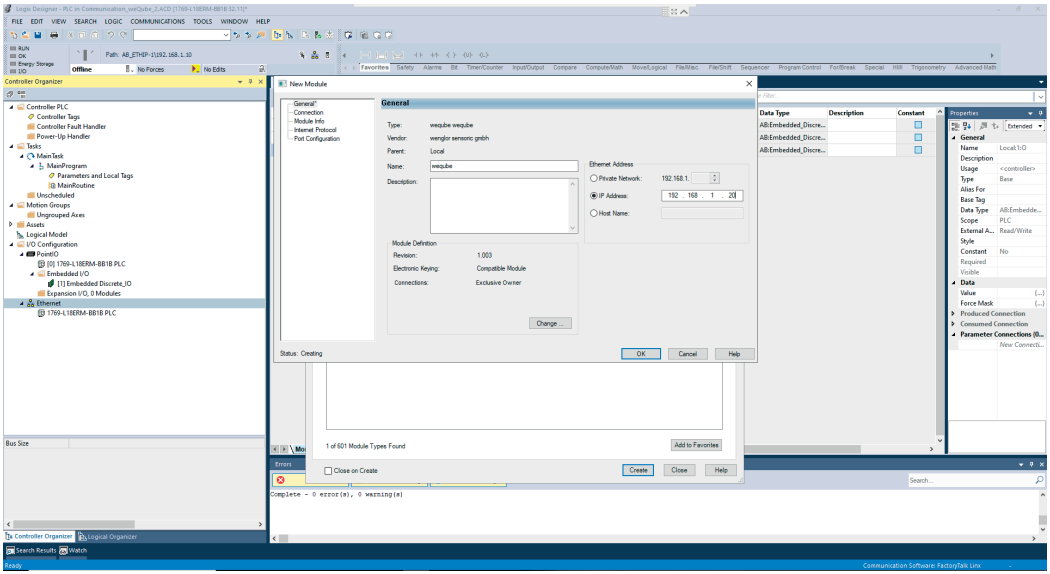
Enter the device name and the network configuration of the device. In the example, the IP address 192.168.1.20 and the name weqube is used.

NOTE!
It is necessary to use the same network configuration and the same device name on the PLC side and on the software for uniVision side.



7.3 Configure Input and Output Data

Click on “Change” in order to setup the input and output data.

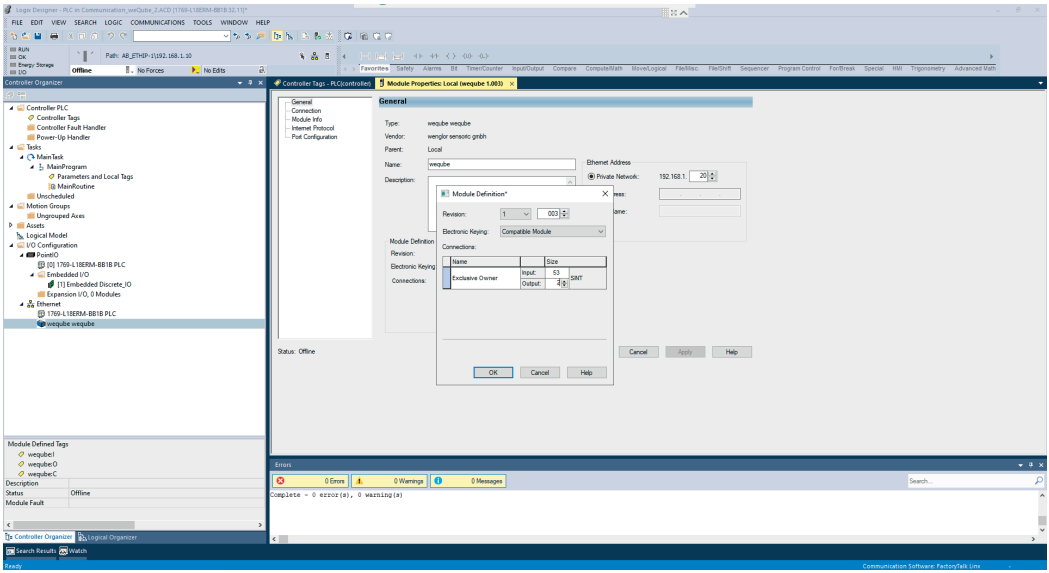


Adjust the input and output size according to the current uniVision project configuration.

NOTE!
Slot 1 (1 Byte Output for project number) and Slot 2 (4 Bytes Input for status) are always present and must be added to the user-defined slots 3-6.

The example (Input: 53 Bytes and Output: 2 Bytes) works for the following slot configuration:

- Slot 1 (fix): 1 Byte Output (Project number)
- Slot 2 (fix): 4 Bytes Input (Status)
- Slot 3: 1 Byte Output (8 BOOL)
- Slot 4: 1 Byte Input (8 BOOL)
- Slot 5: 32 Byte Input (2 CHAR)
- Slot 6: 16 Byte Input (4 DINT)



Click on Apply and on OK.

Open the “Controller Tags”, select weqube:C and set the Module IDs according to the uniVision project configuration.

The Module IDs of slot 1 and slot 2 are set automatically. The Module IDs of all other slots must be set individually depending on the uniVision project settings.

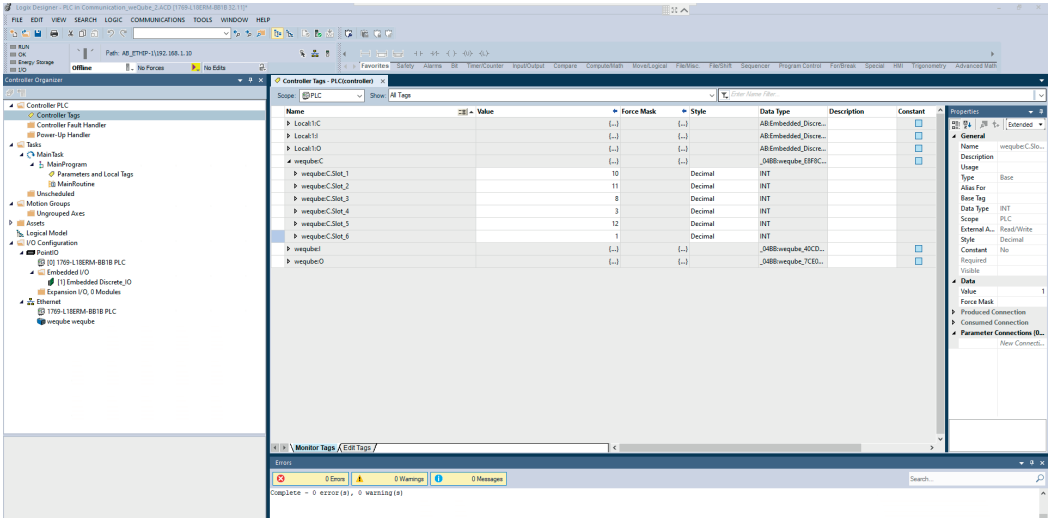
NOTE!
Connect to the Smart Camera via uniVision software in order to check the current Module IDs of the uniVision project (see section "5.2.1 Slots" on page 26)

List of all available Module IDs:

Module ID Hex (Dec)	Description	Direction	Data Length	Representation
0x0000 (0)	Undefined	Undefined	Undefined	Undefined
0x0001 (1)	Process data	weQube → PLC	16 bytes	4 x 4 bytes integer
0x0002 (2)	Process data	weQube → PLC	16 bytes	4 x 4 bytes real
0x0003 (3)	Process data	weQube → PLC	1 byte	8 x 1 bit bool
0x0004 (4)	Process data	weQube → PLC	128 bytes	2 x 64 bytes string
0x0006 (6)	Process data	PLC → weQube	16 bytes	4 x 4 bytes integer
0x0007 (7)	Process data	PLC → weQube	16 bytes	4 x 4 bytes real
0x0008 (8)	Process data	PLC → weQube	1 byte	8 x 1 bit bool
0x0009 (9)	Process data	PLC → weQube	128 bytes	2 x 64 bytes string
0x000A (10)	Project number	PLC → weQube	1 byte	1 x 1 Byte
0x000B (11)	Device State	weQube → PLC	4 bytes	1 x 4 bytes integer
0x000C (12)	Process data	weQube → PLC	32 bytes	2 x 16 bytes string
0x000D (13)	Process data	weQube → PLC	64 bytes	2 x 32 bytes string
0x000E (14)	Process data	weQube → PLC	256 bytes	2 x 128 bytes string
0x0010 (16)	Process data	PLC → weQube	32 bytes	2 x 16 bytes string
0x0011 (17)	Process data	PLC → weQube	64 bytes	2 x 32 bytes string
0x0012 (18)	Process data	PLC → weQube	256 bytes	2 x 128 bytes string

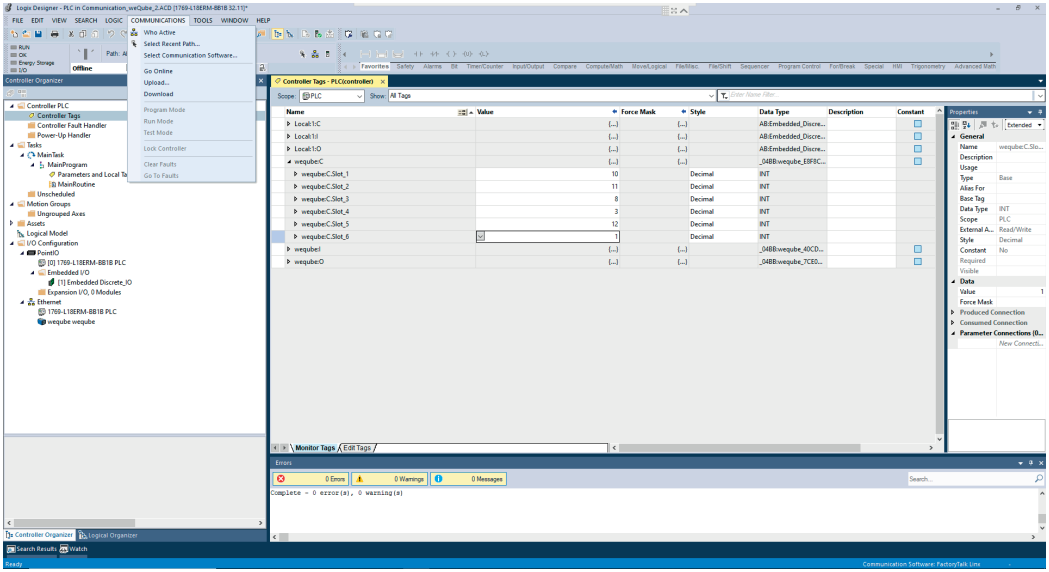
In the example, the following Module IDs must be set:

- Slot 1: 10 (fix)
- Slot 2: 11 (fix)
- Slot 3: 8
- Slot 4: 3
- Slot 5: 12
- Slot 6: 1

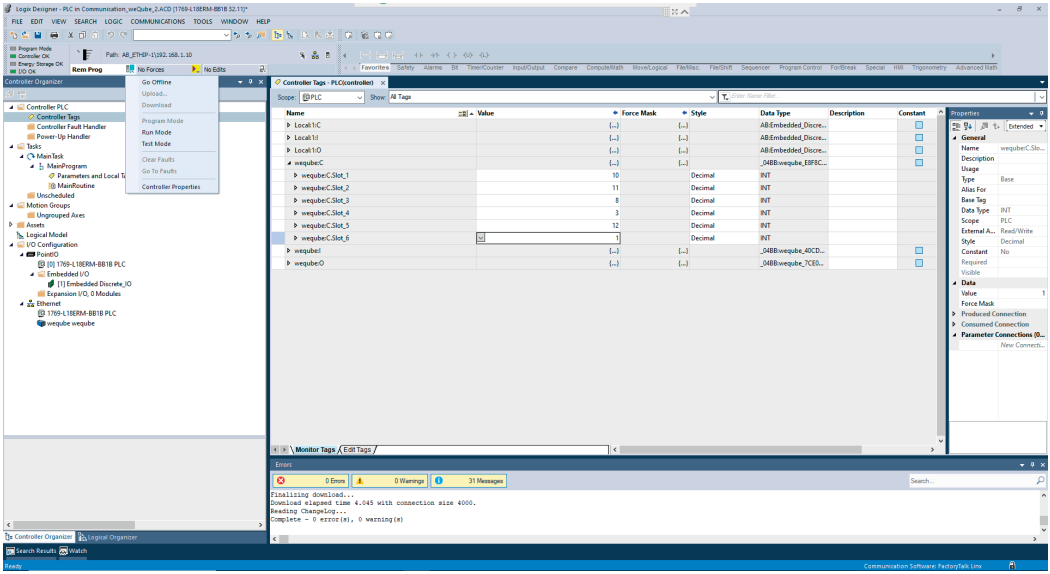


7.4 Download Configuration to PLC

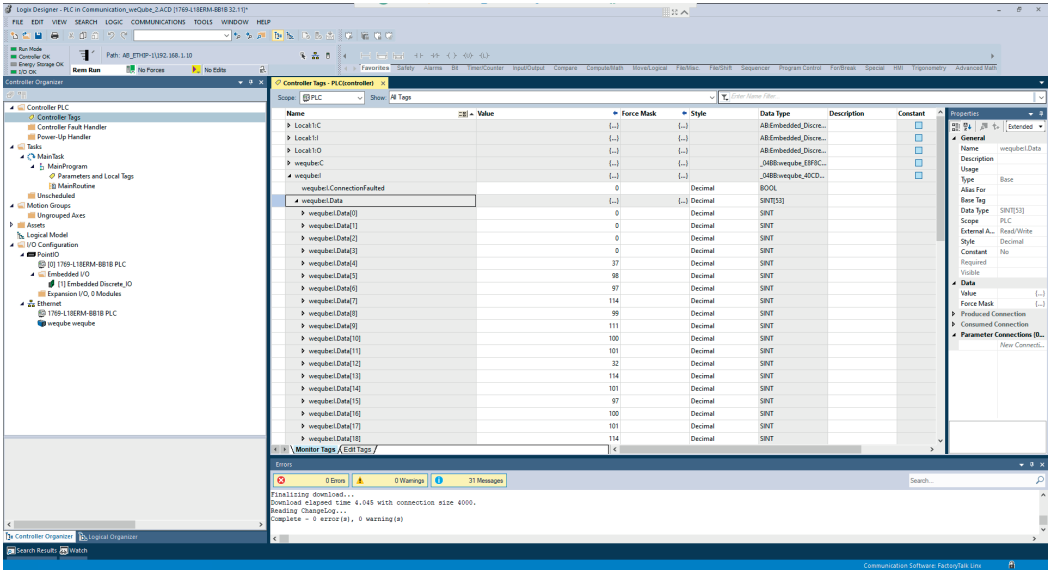
Click on “Communications” → “Download” in order to download the current configuration to the PLC.



Select “Run Mode” to update the input and output data.



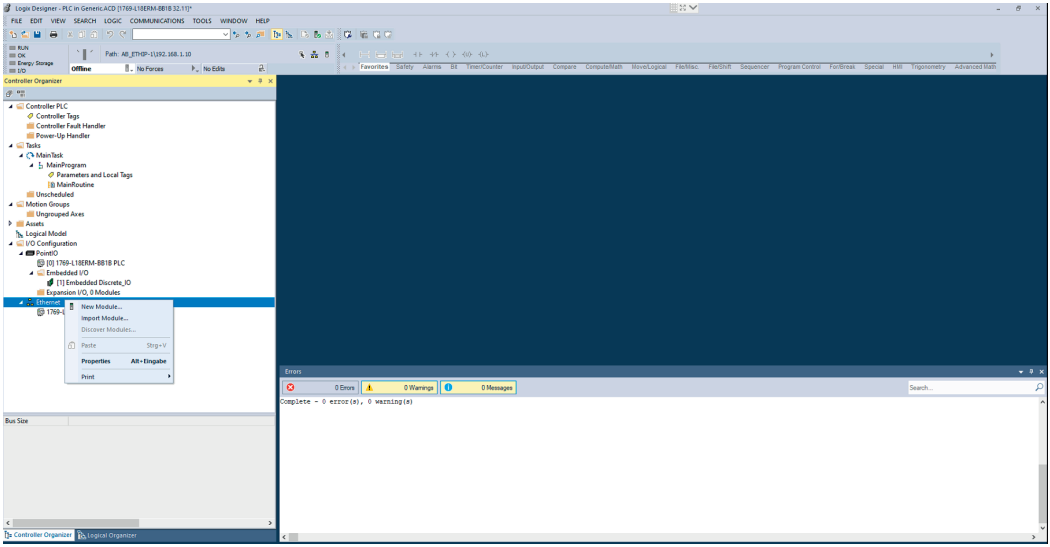
All input and output data of the Smart Camera is available at weqube:I and weqube:O.



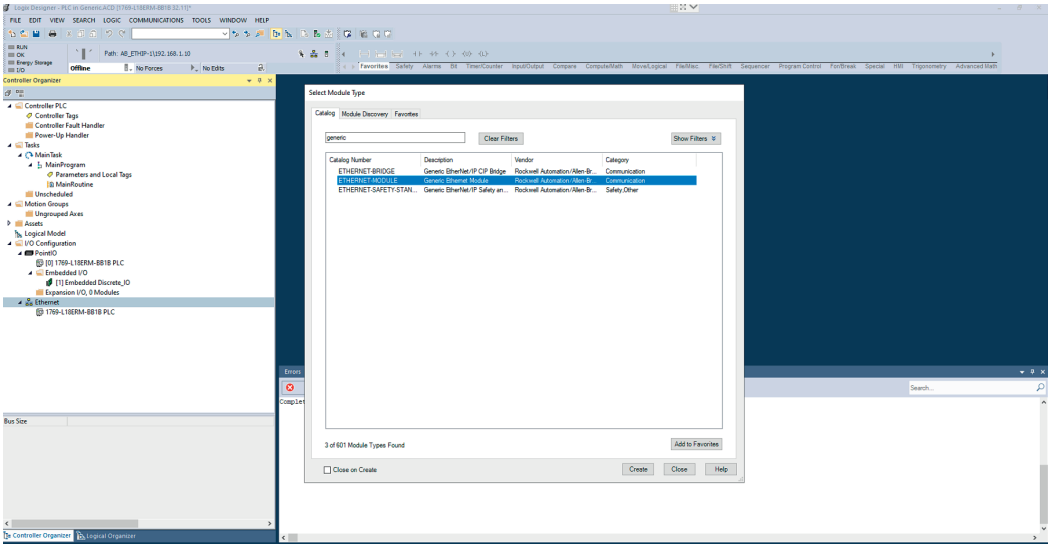
7.5 Integrate Smart Camera without EDS file

In case of some old Rockwell PLCs, EDS files are not supported. Consequently the Smart Camera must be added as generic device.

Open with a right click the context menu at "Ethernet" and select "New Module..." to add the Smart Camera to the PLC network.



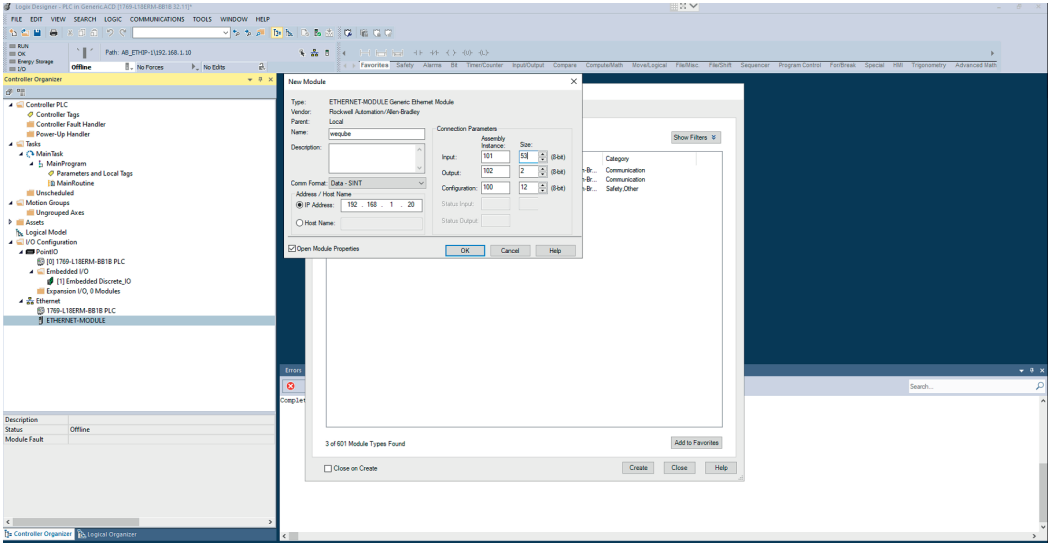
Search for generic and select the "Generic Ethernet Module".



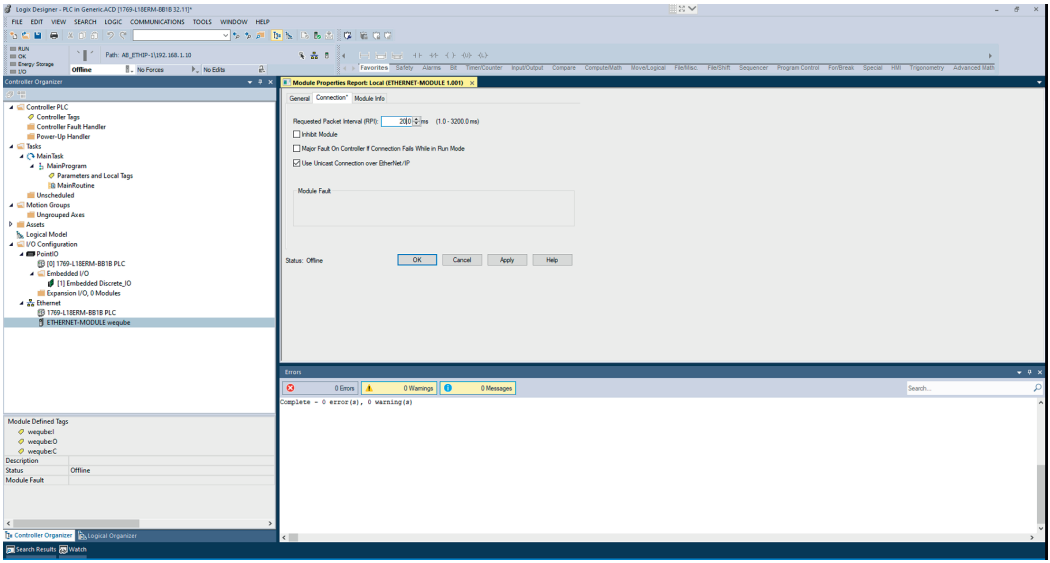
Enter the name and the IP address of the Smart Camera. Set the Communication Format to "Data - SINT". Furthermore the instances must be configured accordingly:

- Input: Instance 101 with x bytes
- Output: Instance 102 with x bytes
- Configuration: Instance 100 with 12 bytes

NOTE!
The input and output size must fit to the uniVision project configuration! Slot 1 and 2 are always present and must be added to the user-defined slots 3-6.



Set the requested packet interval (RPI) to minimum 20 ms and click on ok.

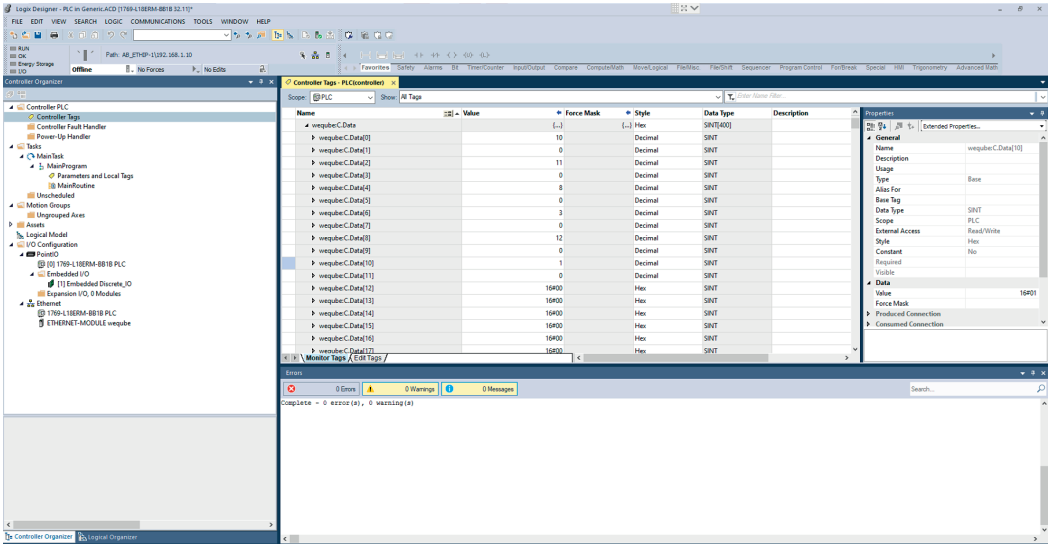


Open the "Controller Tags", select weqube:C and set the Module IDs according to the uniVision project configuration.

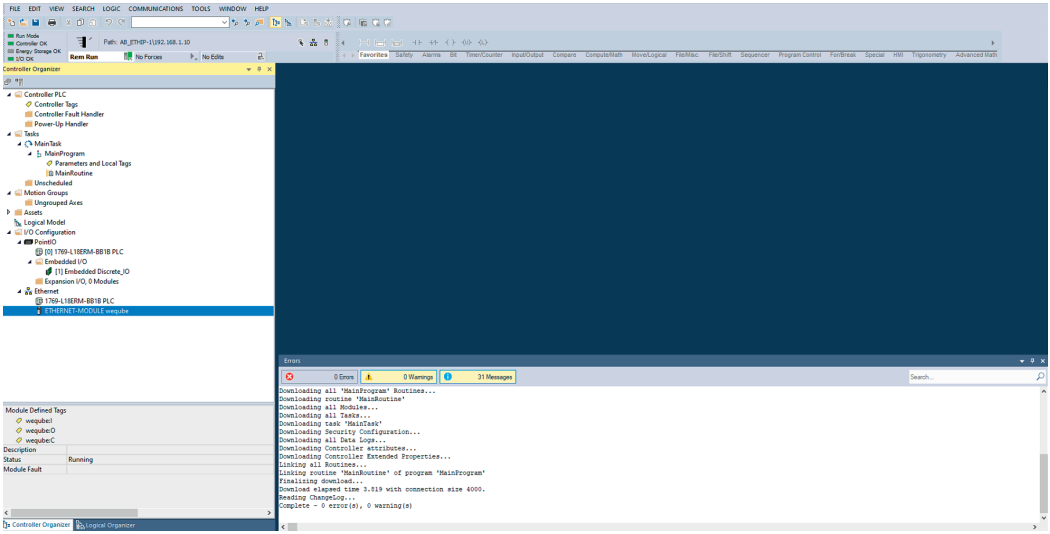
NOTE!
Connect to the Smart Camera via uniVision software in order to check the current Module IDs of the uniVision project (see section "5.2.1 Slots" on page 26).

In the example, the following Module IDs are used:

- weqube:C.Data[0]: 10 (Project number)
- weqube:C.Data[2]: 11 (Status)
- weqube:C.Data[4]: 8 (Module ID of slot 3)
- weqube:C.Data[6]: 3 (Module ID of slot 4)
- weqube:C.Data[8]: 12 (Module ID of slot 5)
- weqube:C.Data[10]: 1 (Module ID of slot 6)



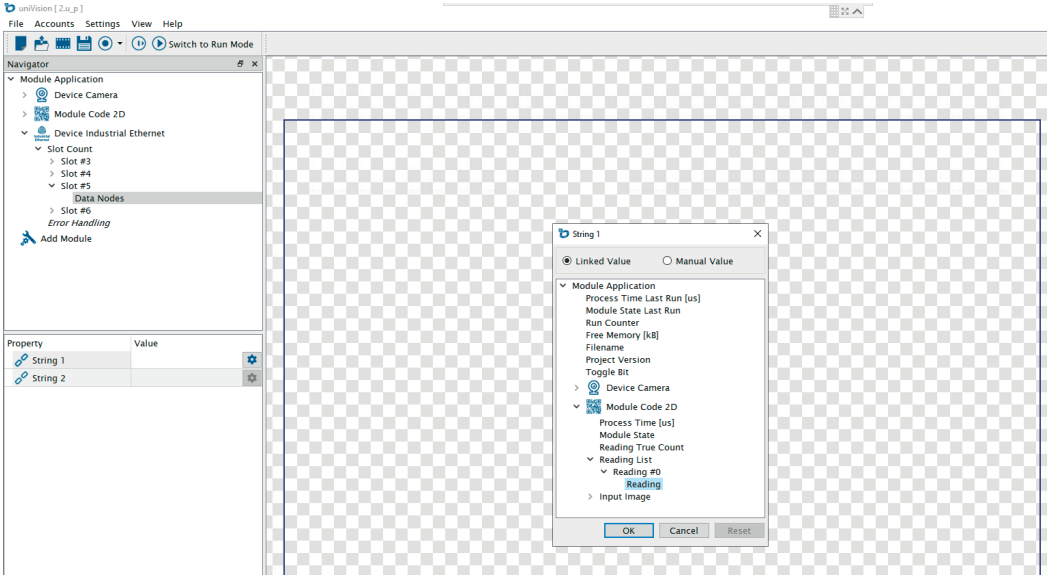
Download the configuration to the PLC and go online.



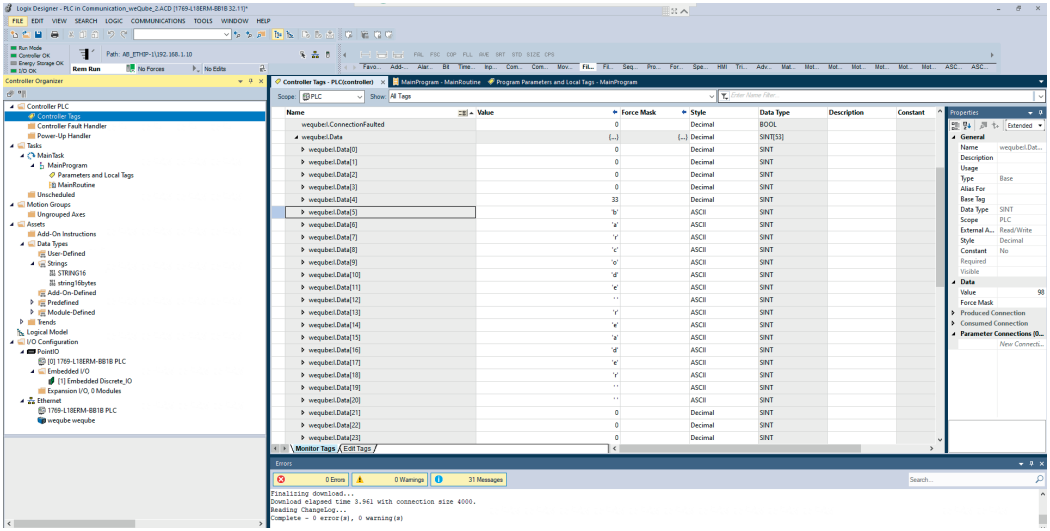
7.6 PLC Parameters and Local Tags

7.6.1 String data

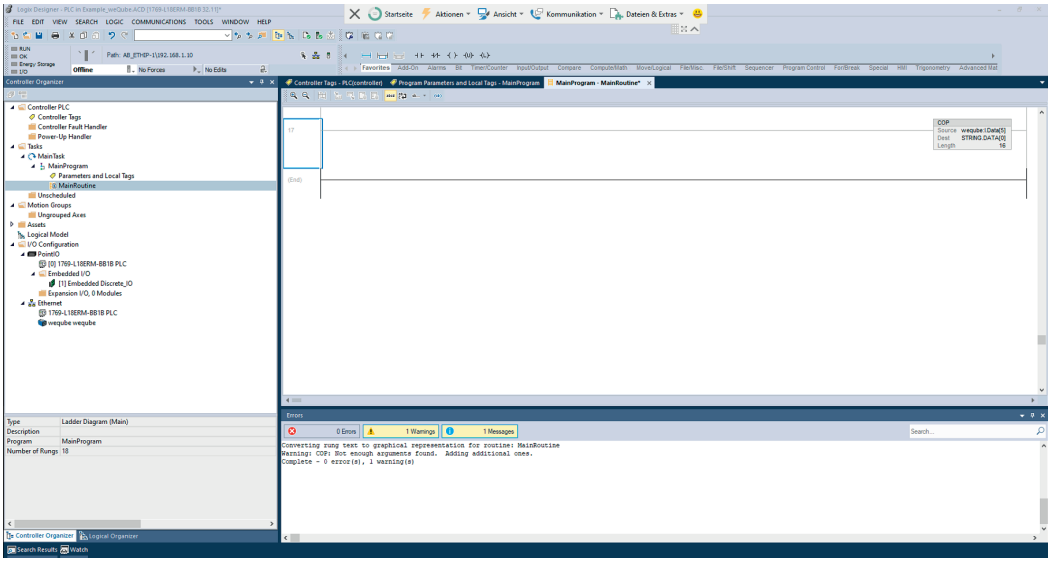
The example shows the sending process of the code result as string 1 in slot 5 (Size: 16 bytes).



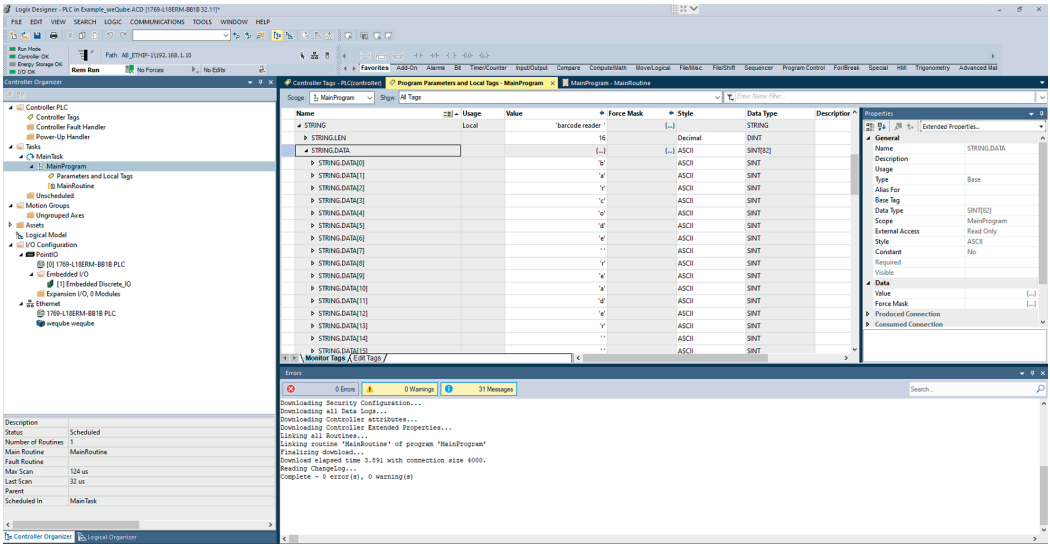
In the software Studio 5000 Logix Designer, the code result is available starting with byte 5 and ending with byte 20.



To copy the bytes in a string, use the FILE COPY (COP) function in the Main Routine. In the example the source is linked to weqube:I.Data[5] and a new string tag with 16 bytes length is created. The destination is set to STRING.Data[0] and the size of the string is set fix to 16 bytes.

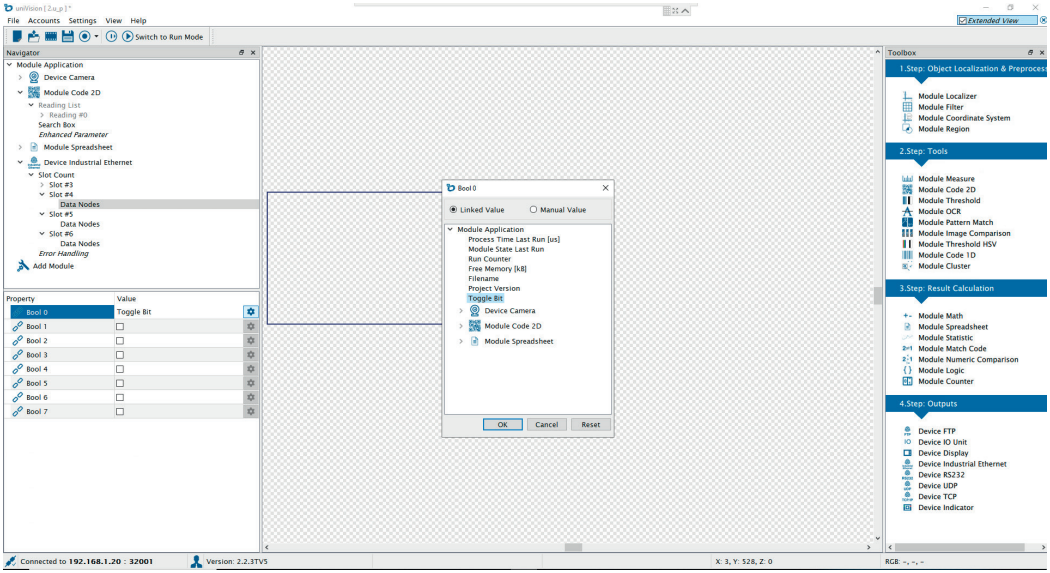


The STRING result is available in the Parameteres and Local Tags.

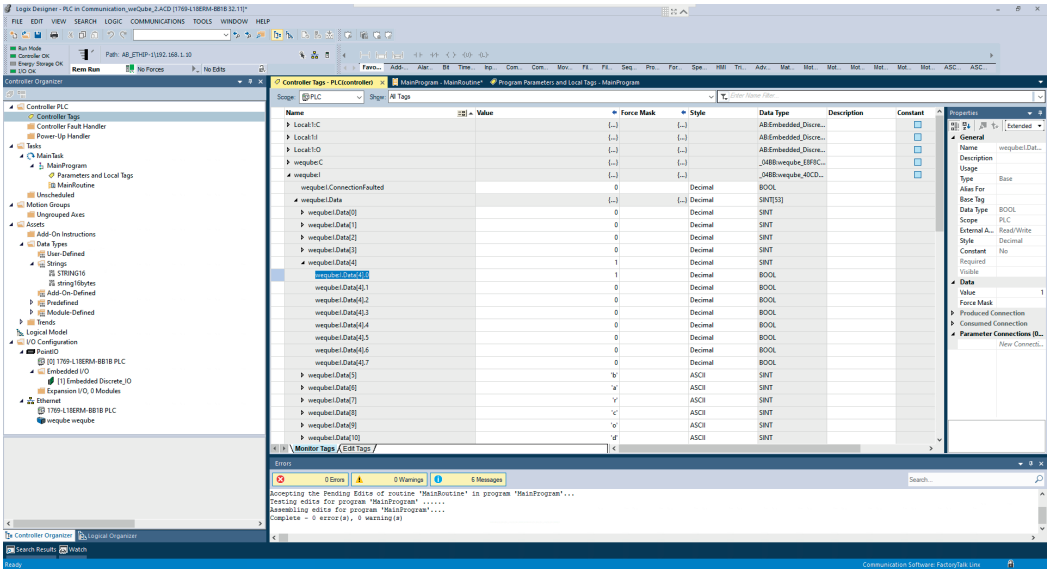


7.6.2 BOOL data

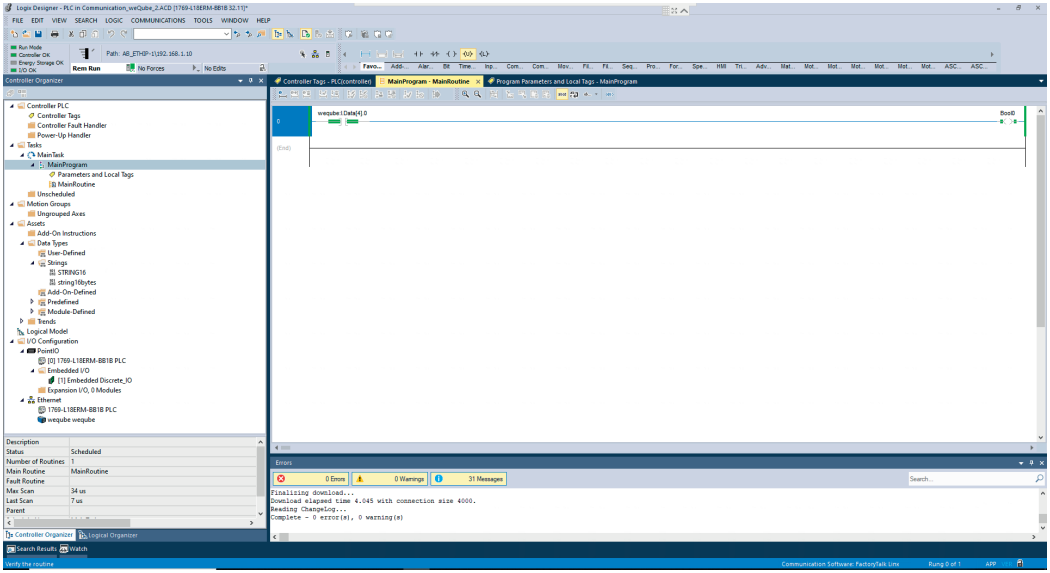
The following example shows linking a boolean result in slot 4 (Bool 0).



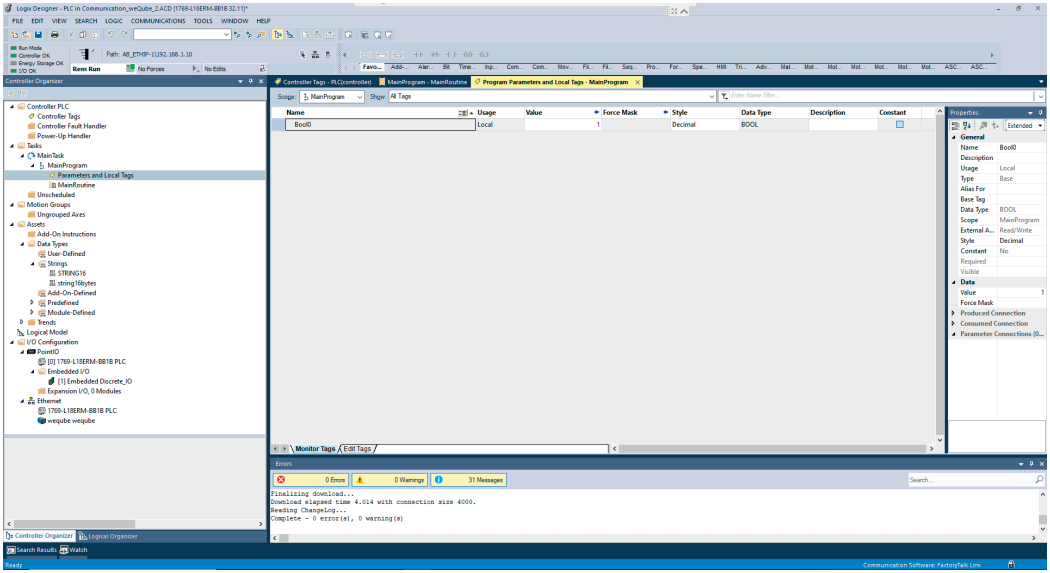
On the PLC, the boolean result is shown at weqube:I.Data[4].0.



To copy the boolean result in a local tag, add the “Examine On” and the “Output Energize” in the Main Routine. Link the “Examine On” to byte 4 bool 0 and link the “Output Energize” to a new boolean tag.



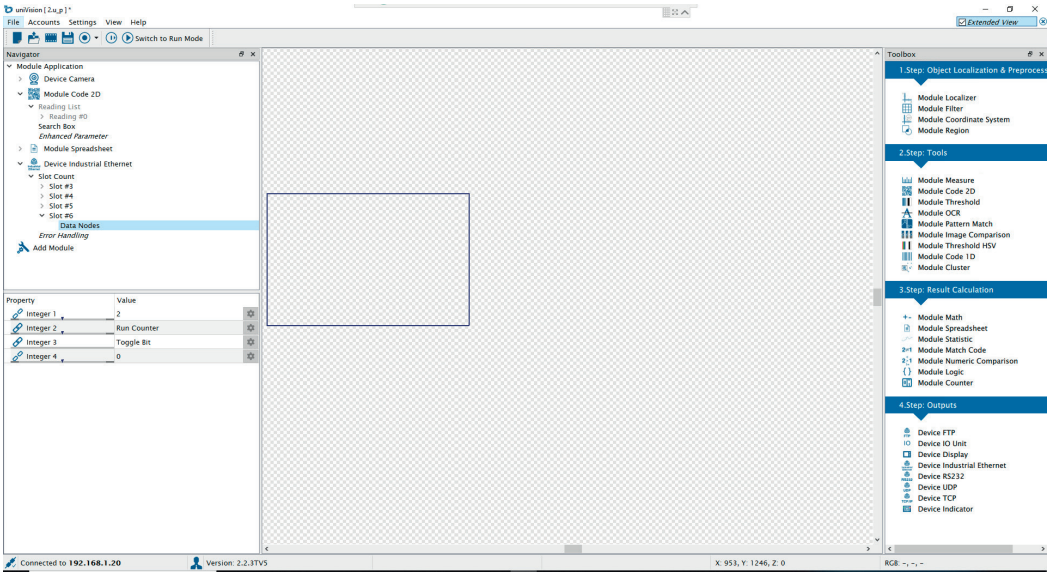
The boolean result is available in the Parameters and Local Tags.



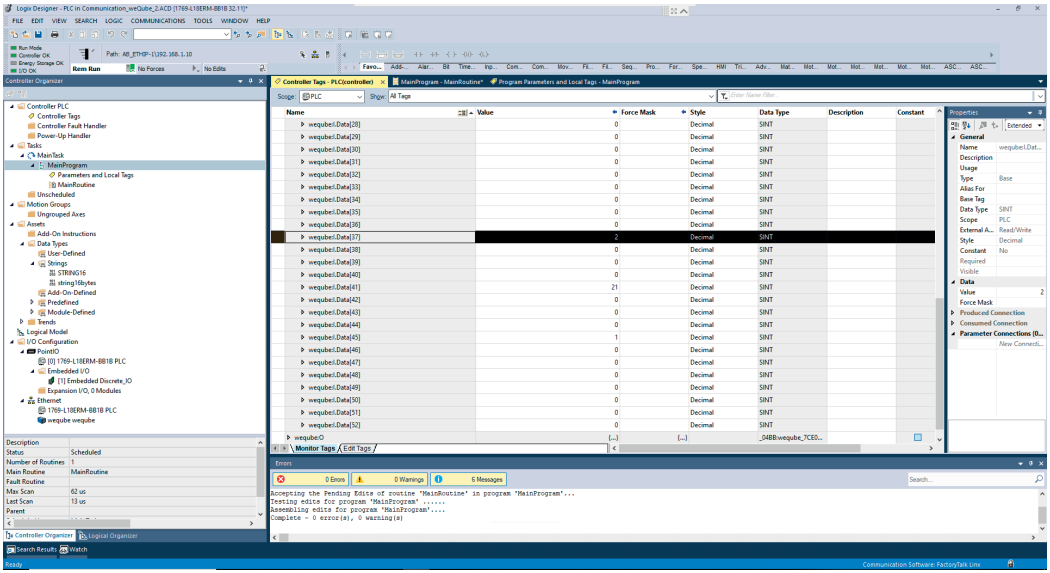
7.6.3 DINT and REAL data

The following example shows linking DINT results in slot 6.

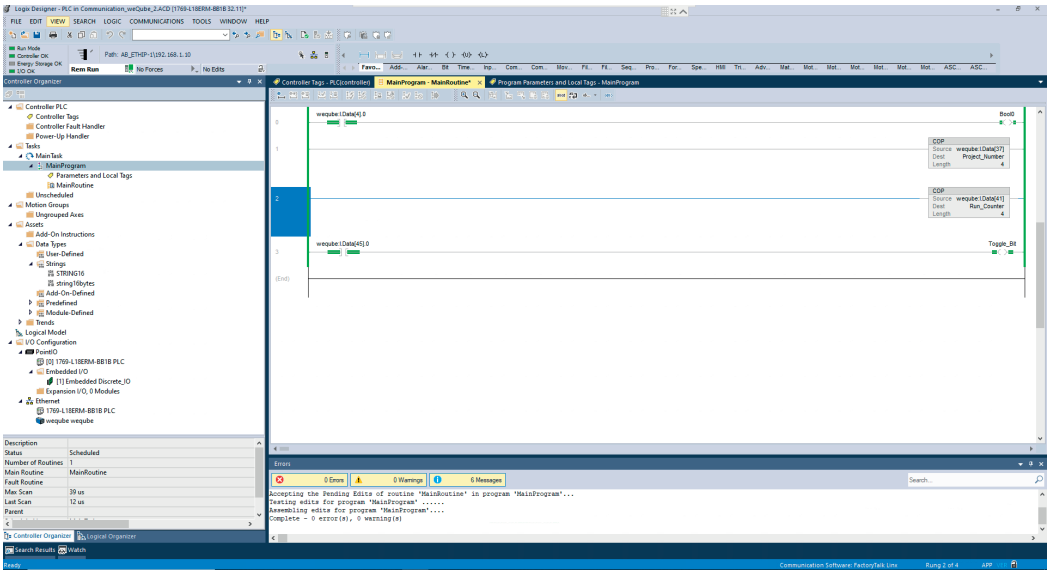
- DINT 1: Project number
- DINT 2: Run Counter
- DINT 3: Toggle Bit



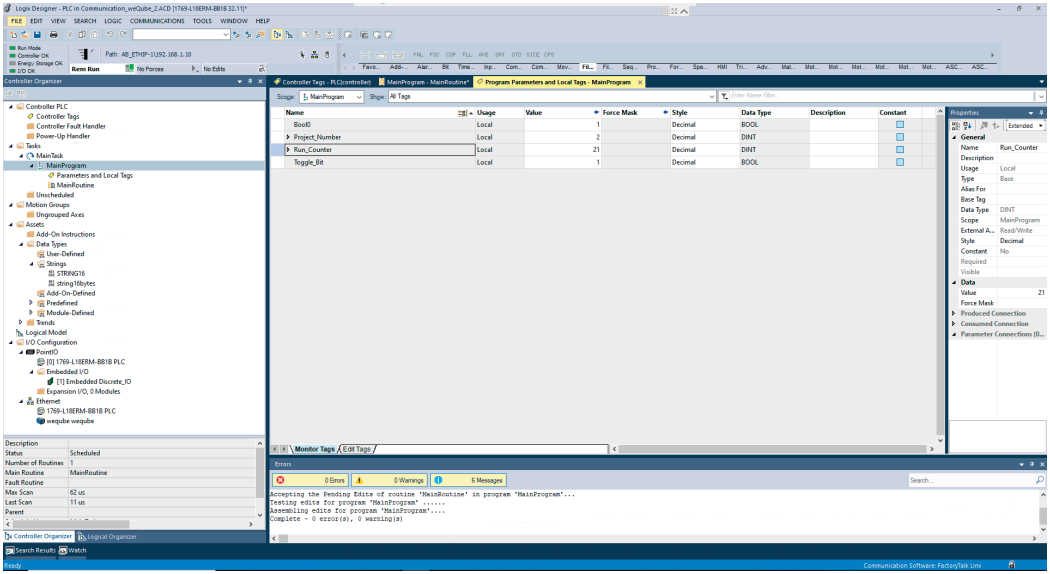
On the PLC, the DINT results are shown in single bytes.



To create DINT results out of the single bytes, use the FILE COPY (COP) function in the Main Routine. In the example, the source is linked to byte 37 for the project number and to byte 41 for the run counter. Create new tags for the destination (with data type DINT and a length of 4 bytes).



The DINT results are available in the Parameters and Local Tags.



NOTE!
REAL data can be copied the same way to Parameters and Local Tags. The only difference is that the data type of the destination must be set to REAL.

NOTE!
Make sure to check the change of the toggle bit and/or the run counter in the last slot in order to check if all measurement results are already updated.

8. PLC Settings at Omron PLCs

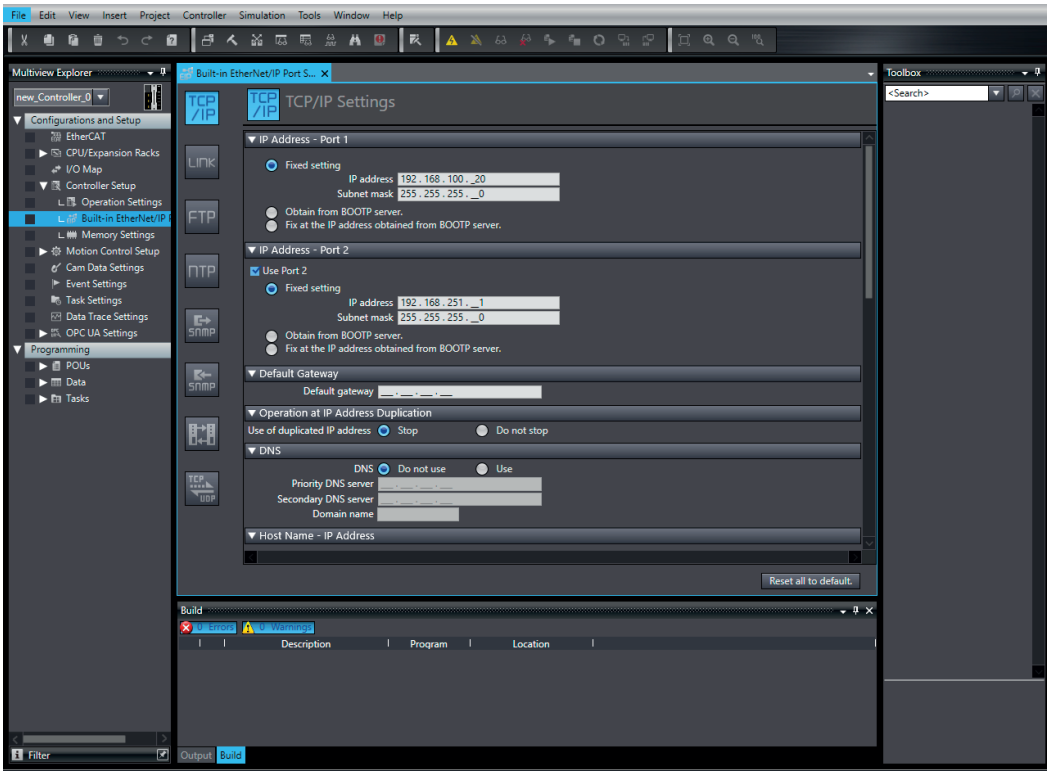
The Smart Camera can also be integrated via EtherNet/IP at Omron PLCs. The following description shows the relevant steps for a NX102-1200 PLC from Omron with Sysmac Studio Version 1.41.0.10.

8.1 Network Settings

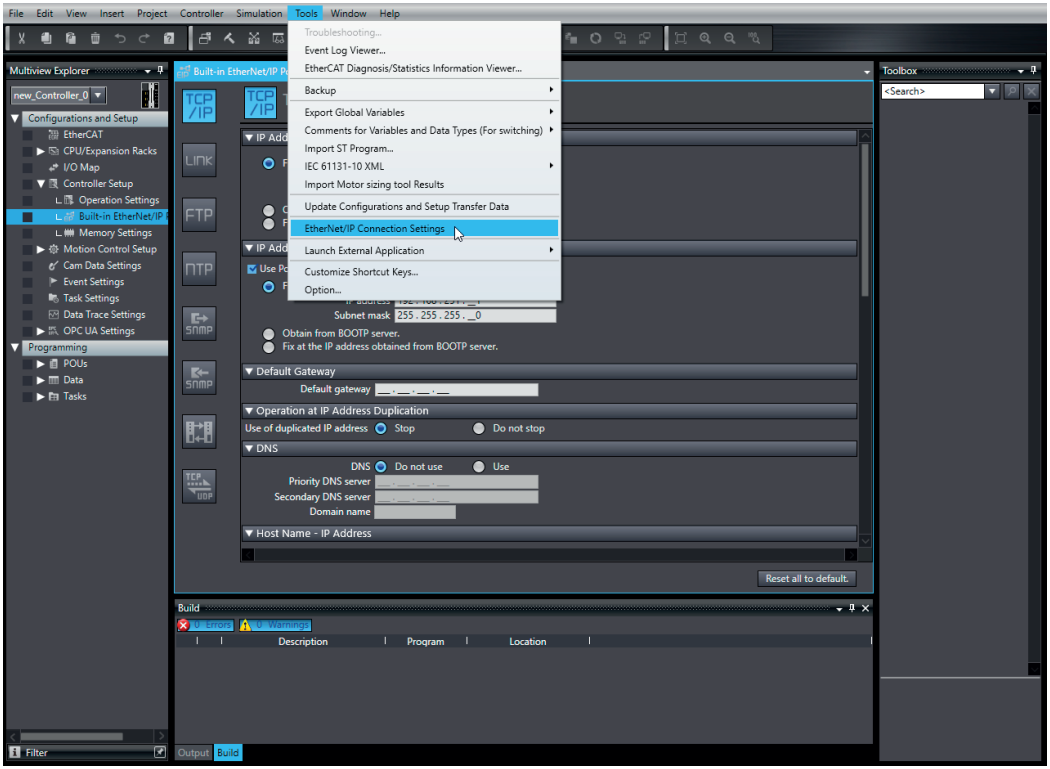
In the example, the following network settings are used:

- PC with Sysmac Studio and uniVision software: IP address 192.168.100.1
- Smart Camera weQube: IP address 192.168.100.15
- PLC: IP address 192.168.100.20

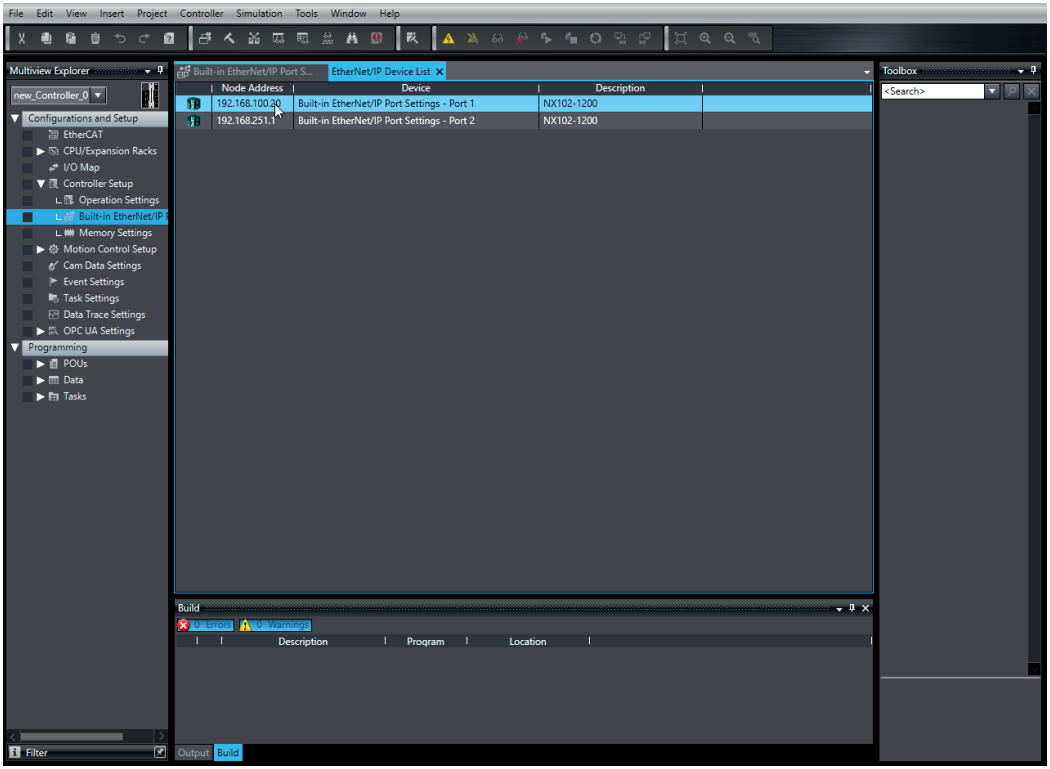
Open Sysmac Studio and define the network settings of the PLC.



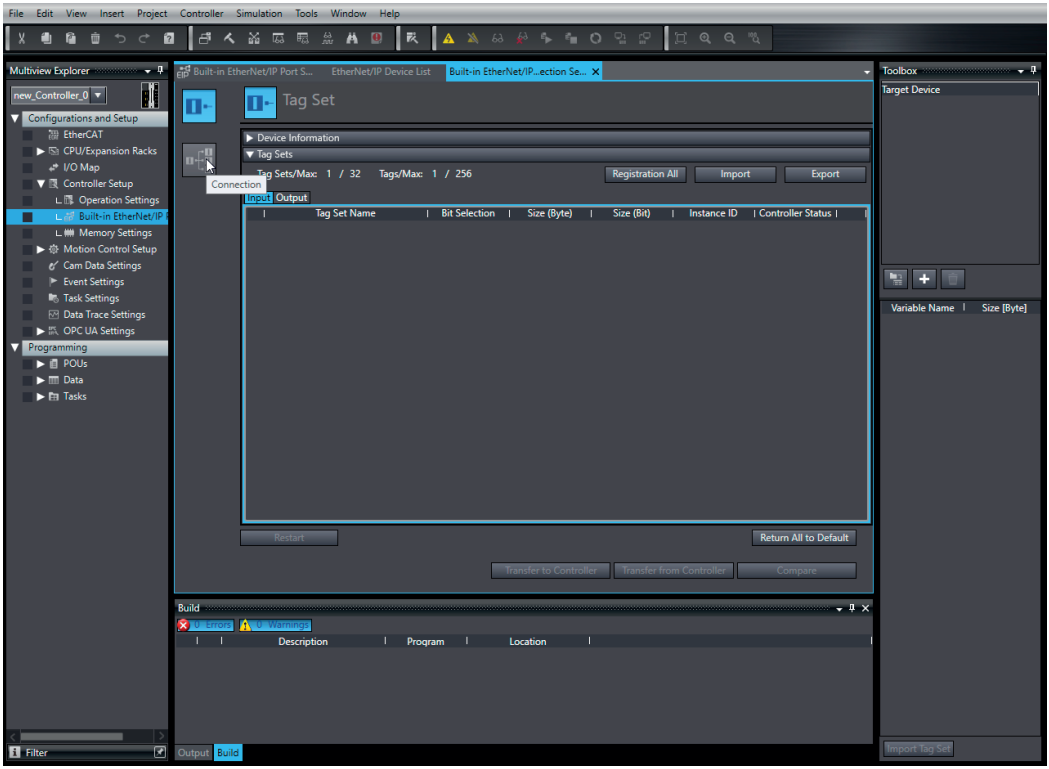
Click on "Tools" → "EtherNet/IP Connection Settings".



Double click on the relevant IP address.

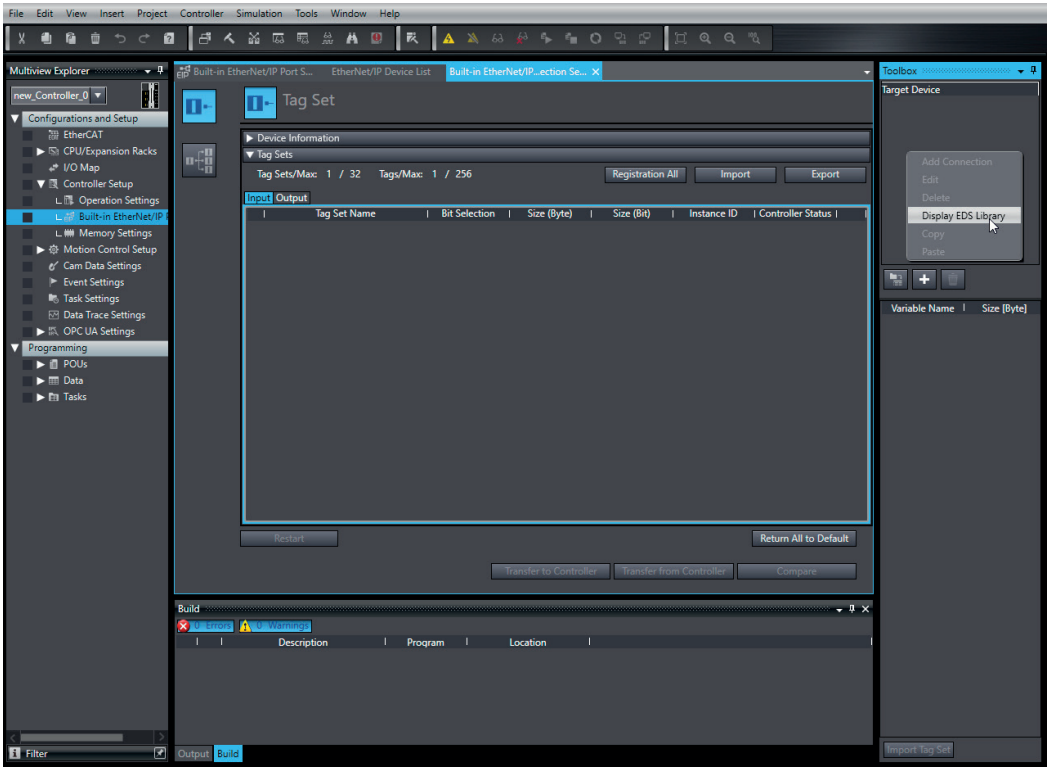


Select the connection button.

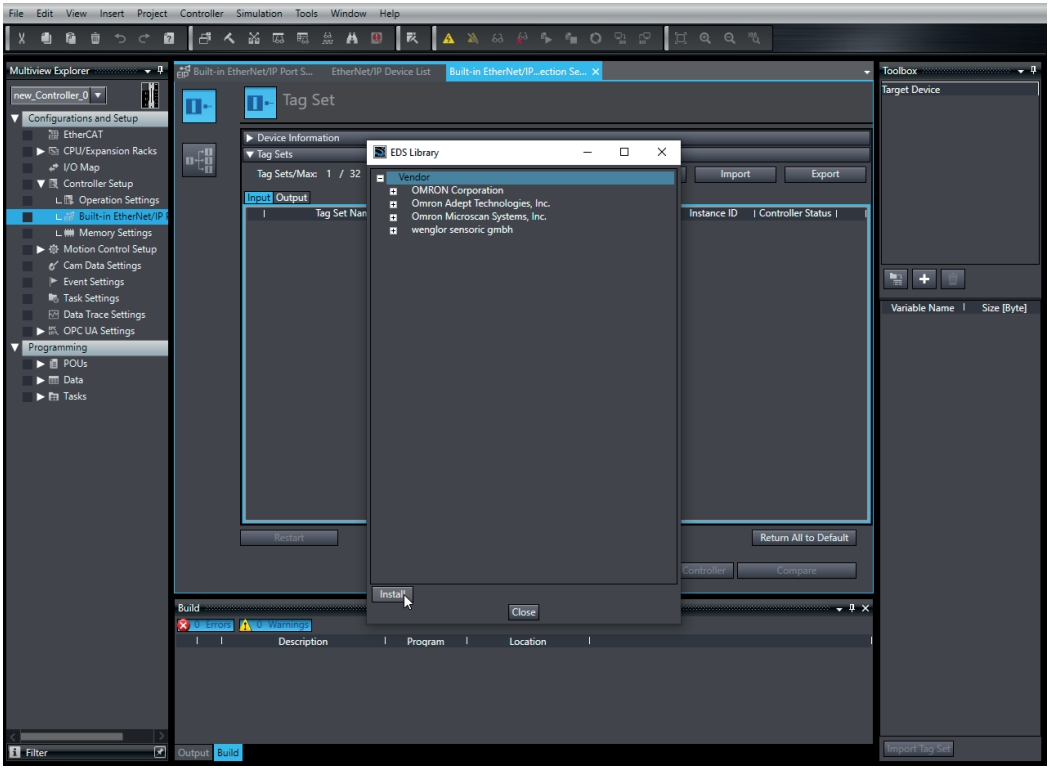


8.2 EDS file

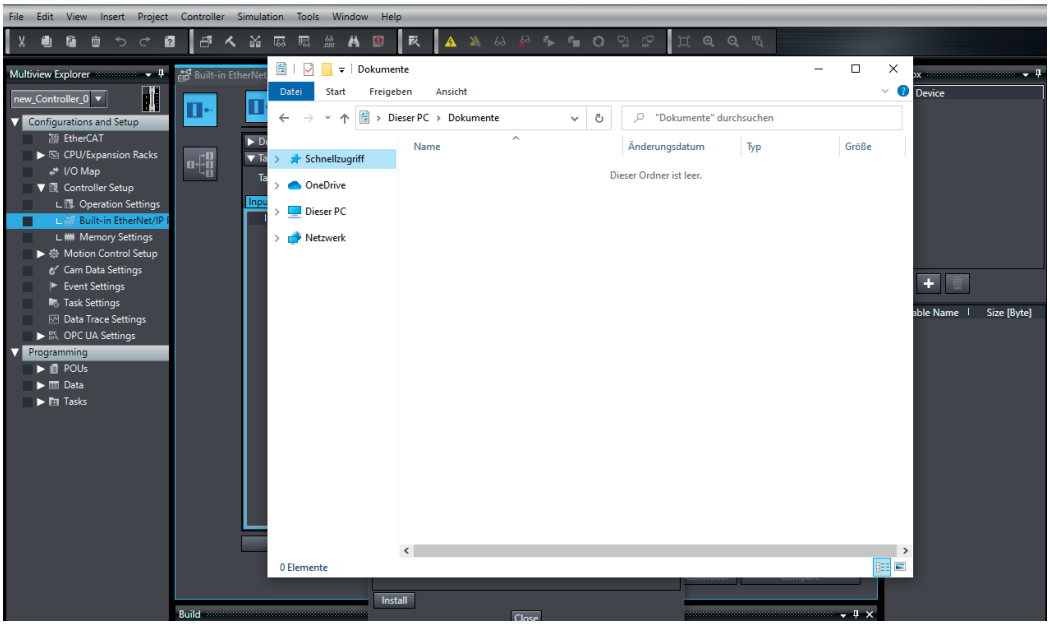
Open the context menu at the toolbox with a right click and select "Display EDS Library".



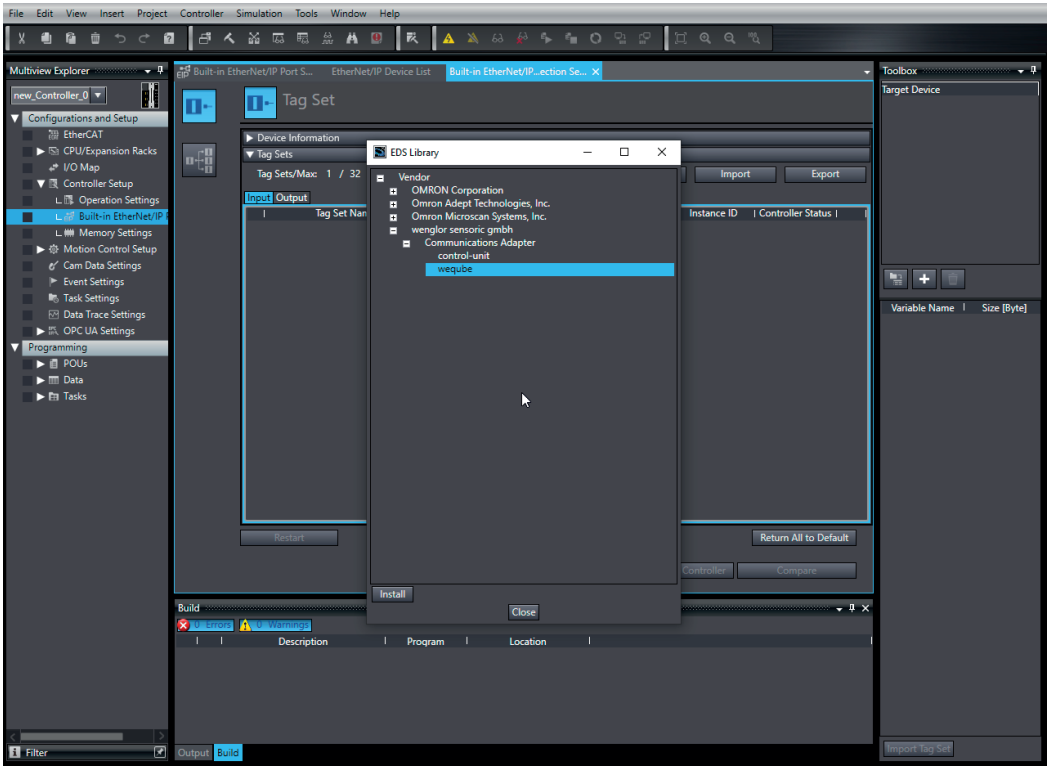
Click on "Install" to install an EDS file.



Select the EDS file of the Smart Camera weQube. Visit www.wenglor.com and search for the article number of the Smart Camera in order to download the EDS file.

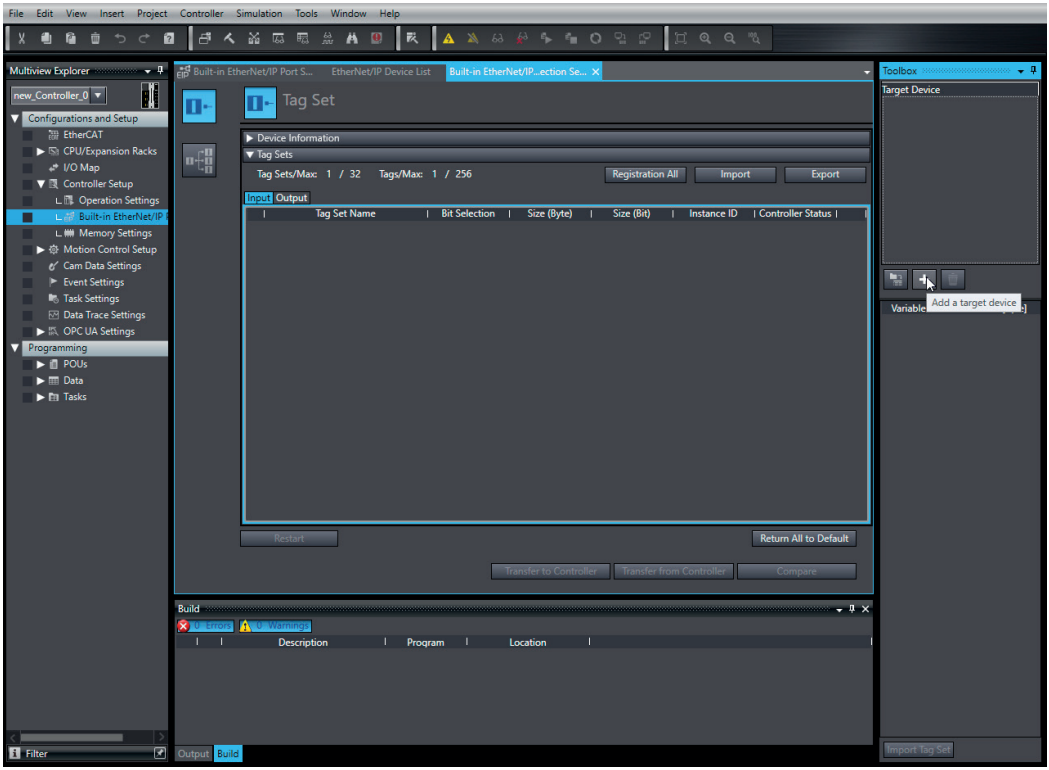


After the installation of the EDS file, it is shown at "wenglor sensoric gmbh" -> "Communications Adapters".

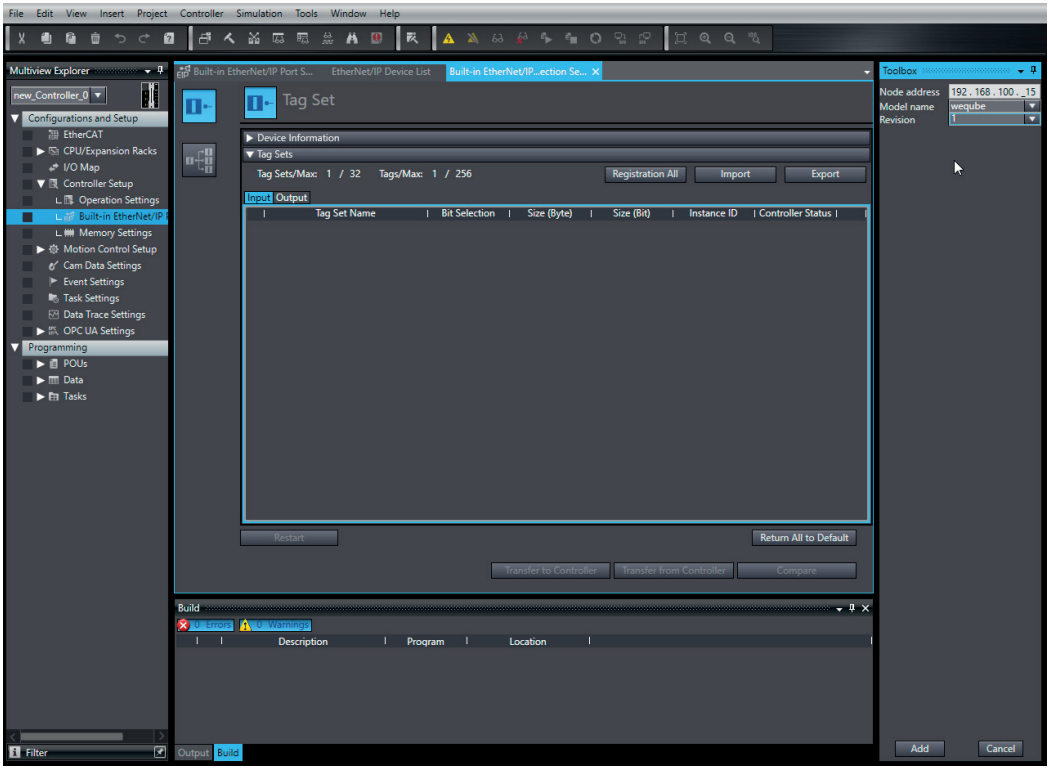


8.3 Add Smart Camera to PLC network

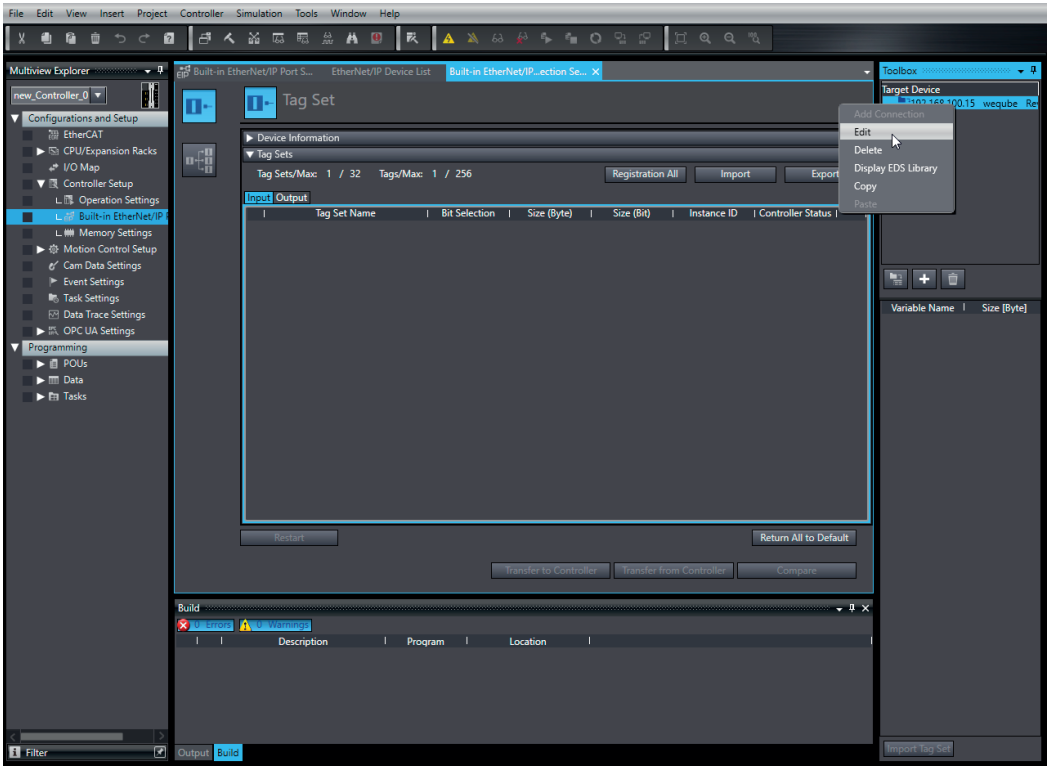
Close the window and click on the add symbol in the "Target Device" window.



Enter the IP address, the name "weqube" and the revision of the Smart Camera and click on "Add".



Open the context menu of the device in order to edit the settings.

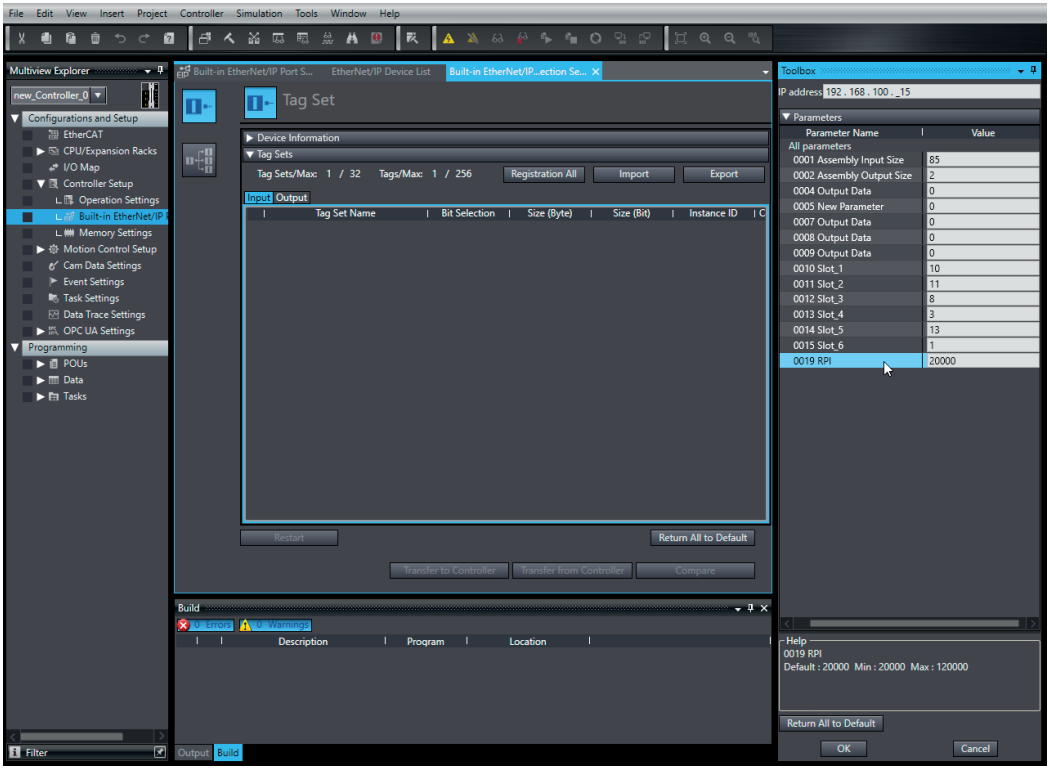


Depending on the settings of the uniVision project, the size and the Module IDs for all slots must be set. In the example, the following slots are used:

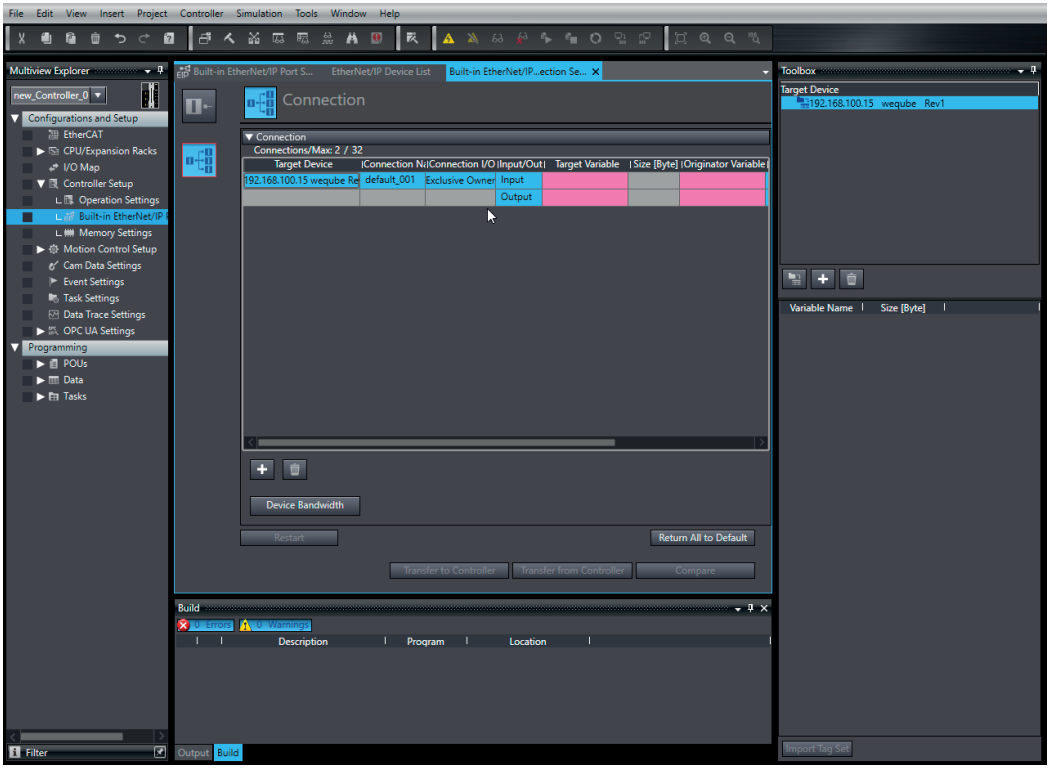
- Slot 1: Project number (fix)
- Slot 2: Module Status (fix)
- Slot 3: 1 Byte Output (8 BOOL)
- Slot 4: 1 Byte Input (8 BOOL)
- Slot 5: 64 Byte Input (2 CHAR)
- Slot 6: 16 Byte Input (4 DINT)

Consequently, the following settings must be done:

- Assembly Input Size: 85 bytes
- Assembly Output Size: 2 bytes
- Slot_1 (Module ID): 10
- Slot_2 (Module ID): 11
- Slot_3 (Module ID): 8
- Slot_4 (Module ID): 3
- Slot_5 (Module ID): 13
- Slot 6 (Module ID): 1
- RPI: 20000 µs

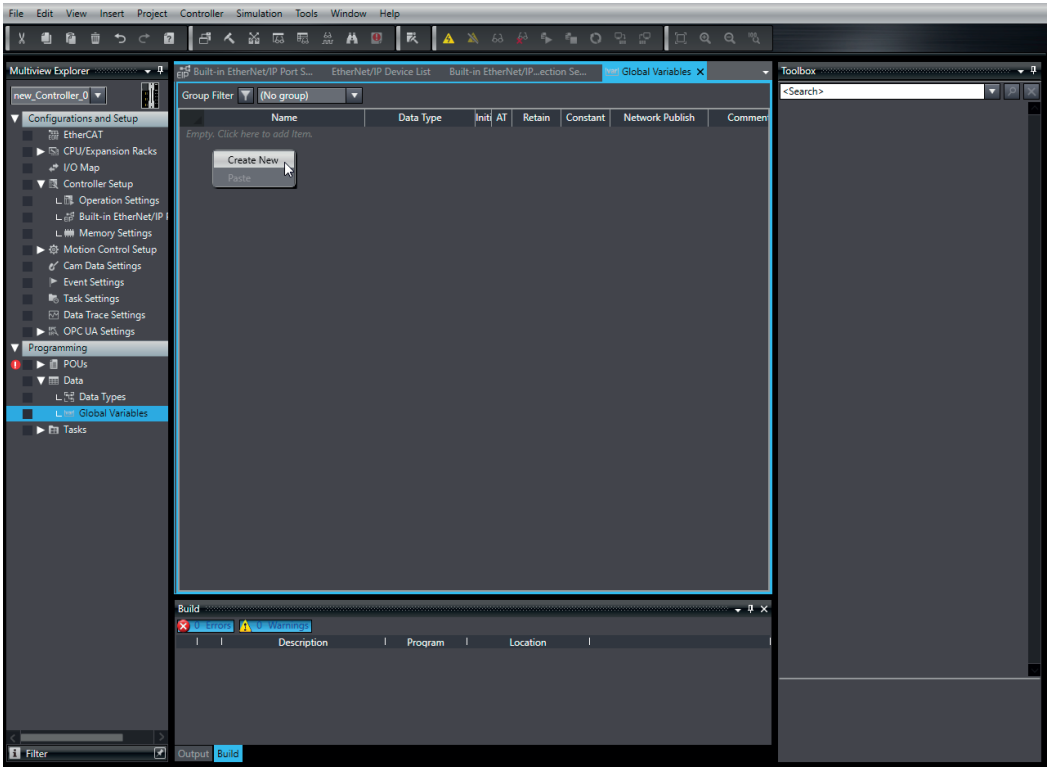


Add the weQube to the connections.

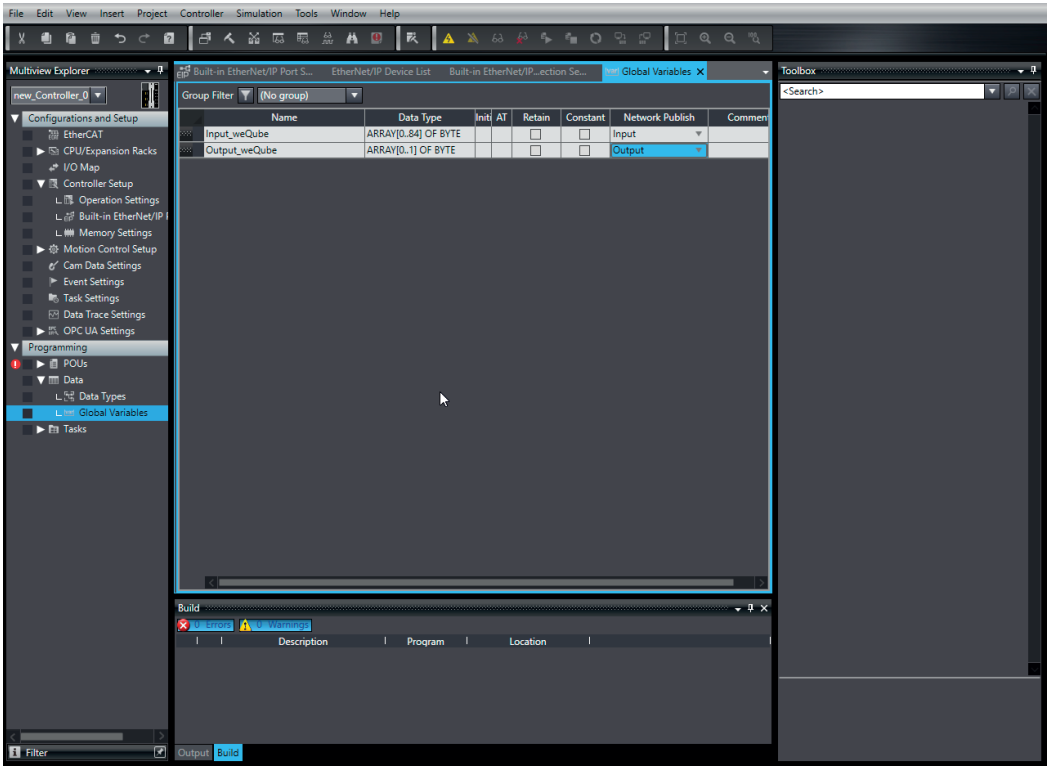


8.4 Configure Input and Output Data

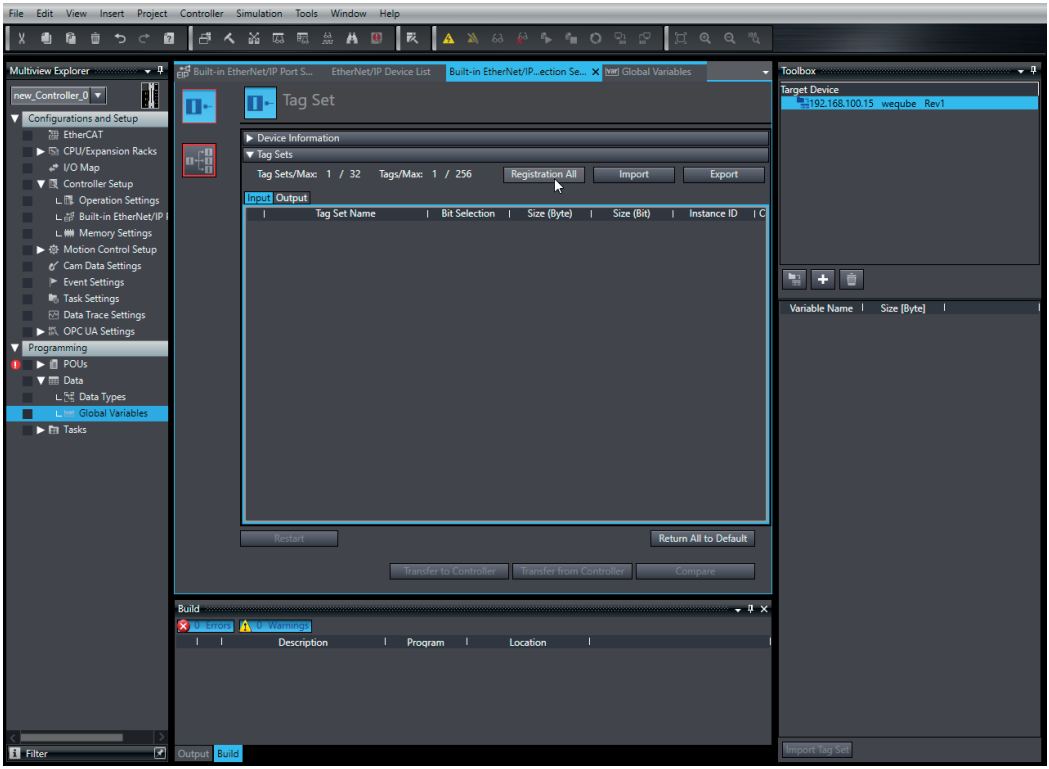
Open the global variables and create new variables.



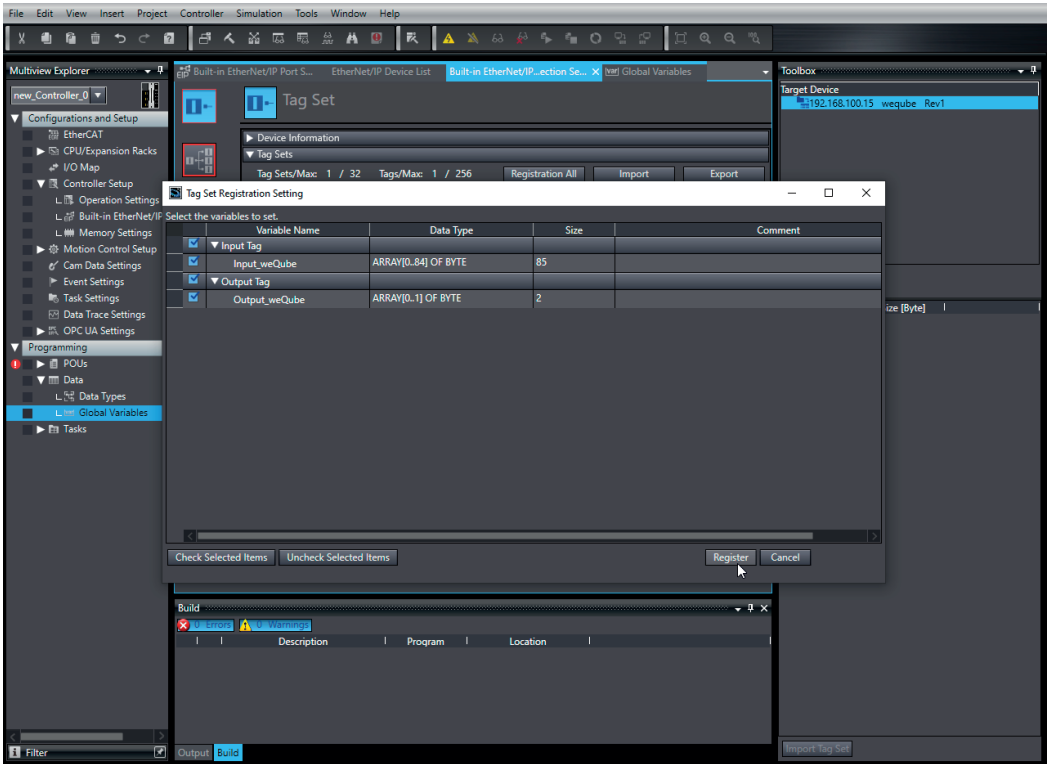
One array of bytes is necessary for the input data and one output array of bytes is needed for the output data.



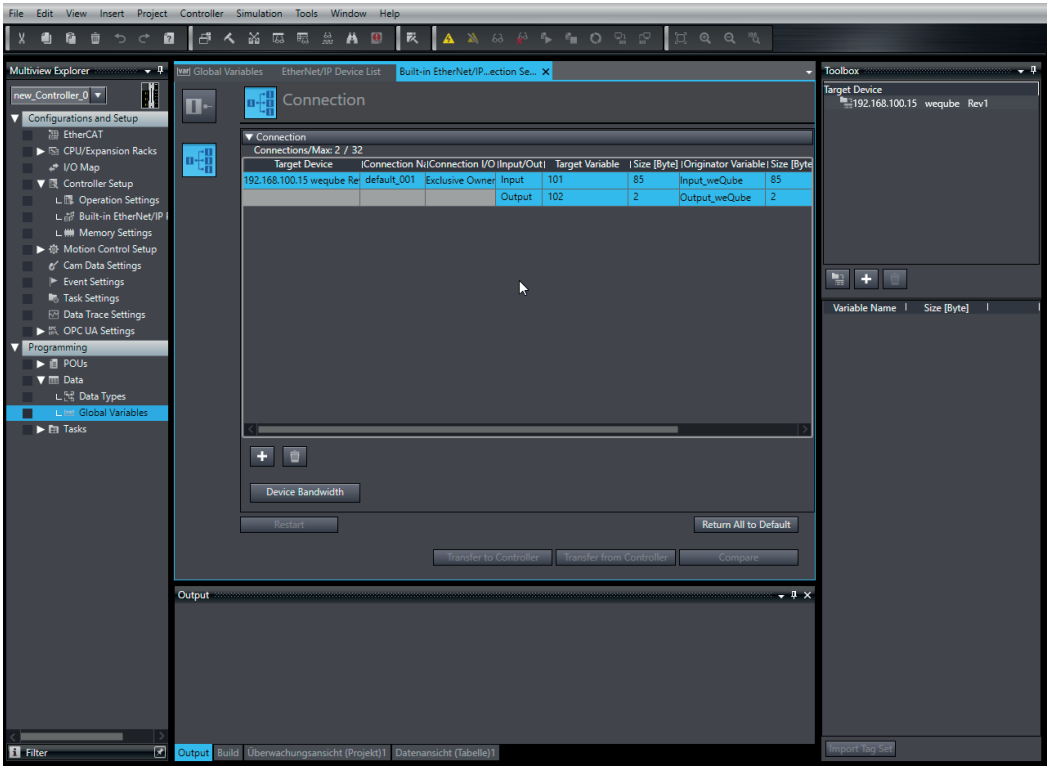
Switch to the tag definition and click on "Registration All.



Select all and click on "Register".

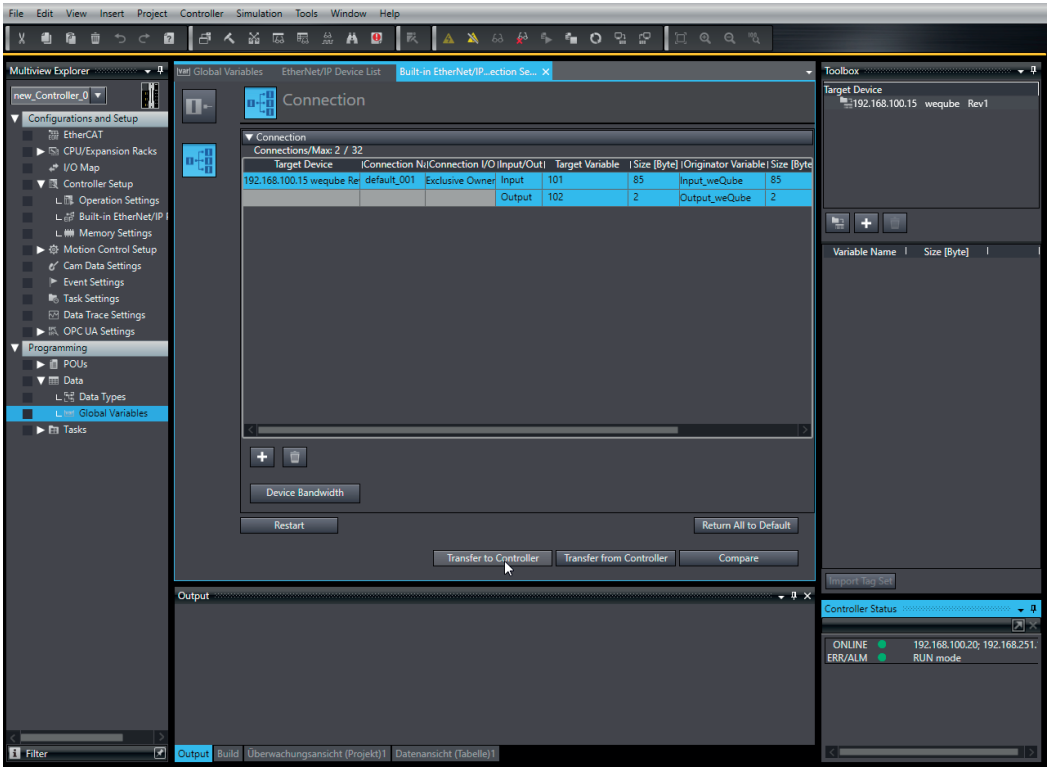


Select in the connections the input and output variables.

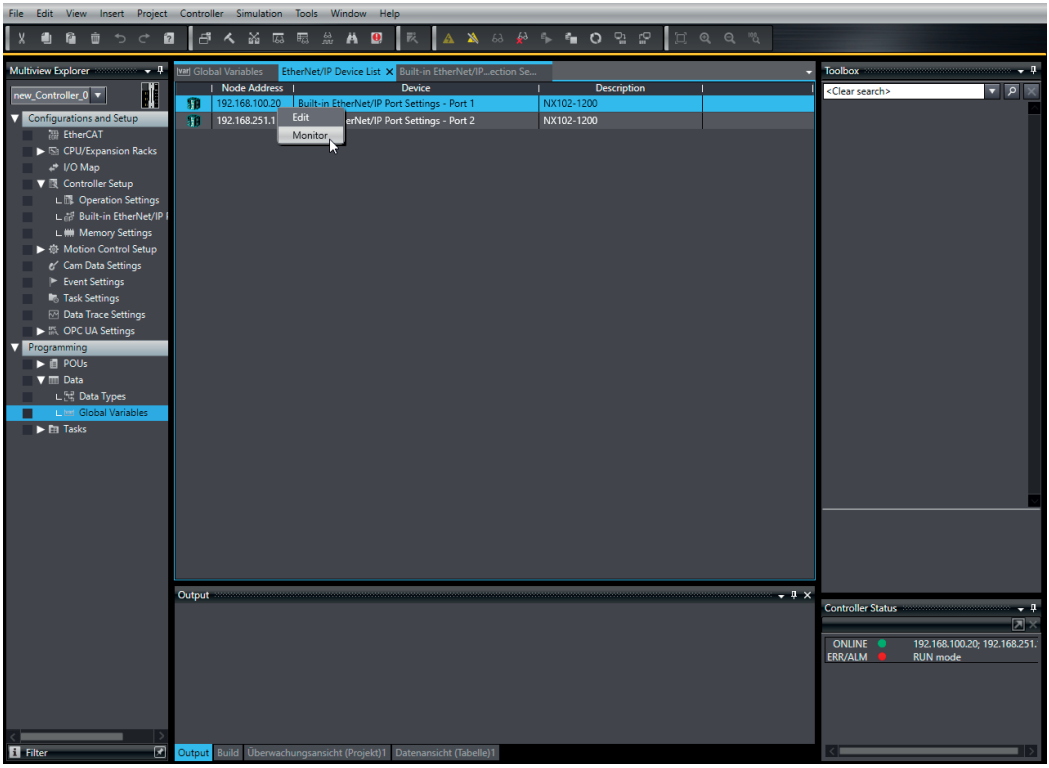


8.5 Download Configuration to PLC

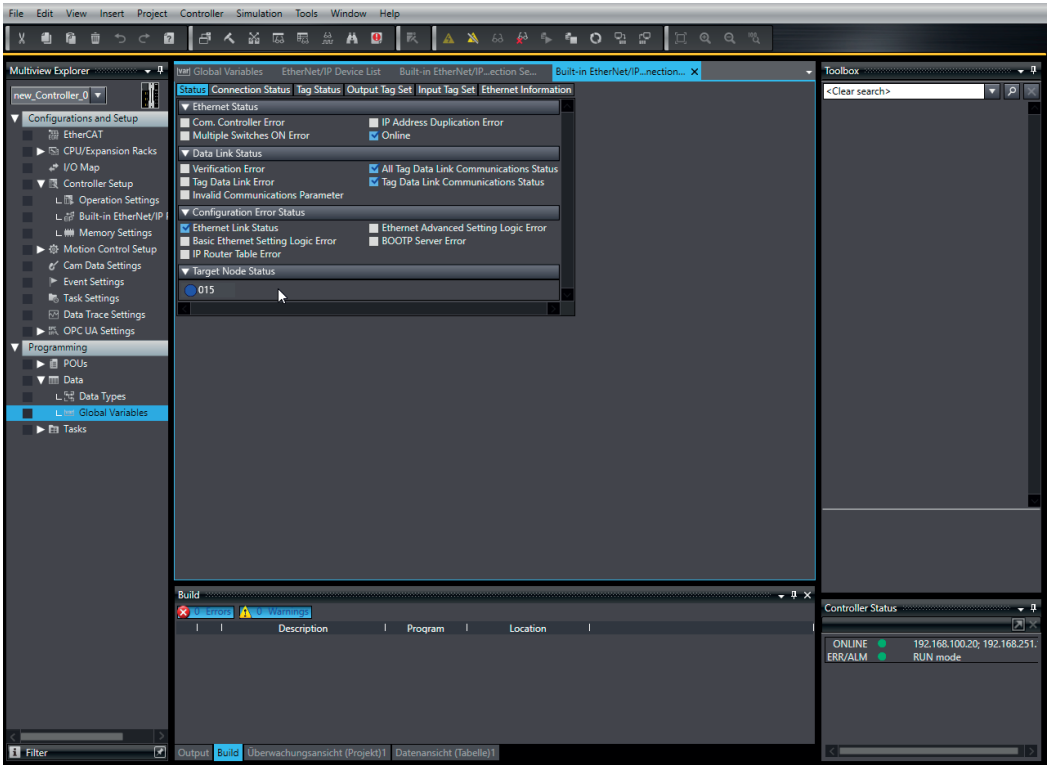
Go online and select "Transfer to Controller" to send the configuration to the PLC.



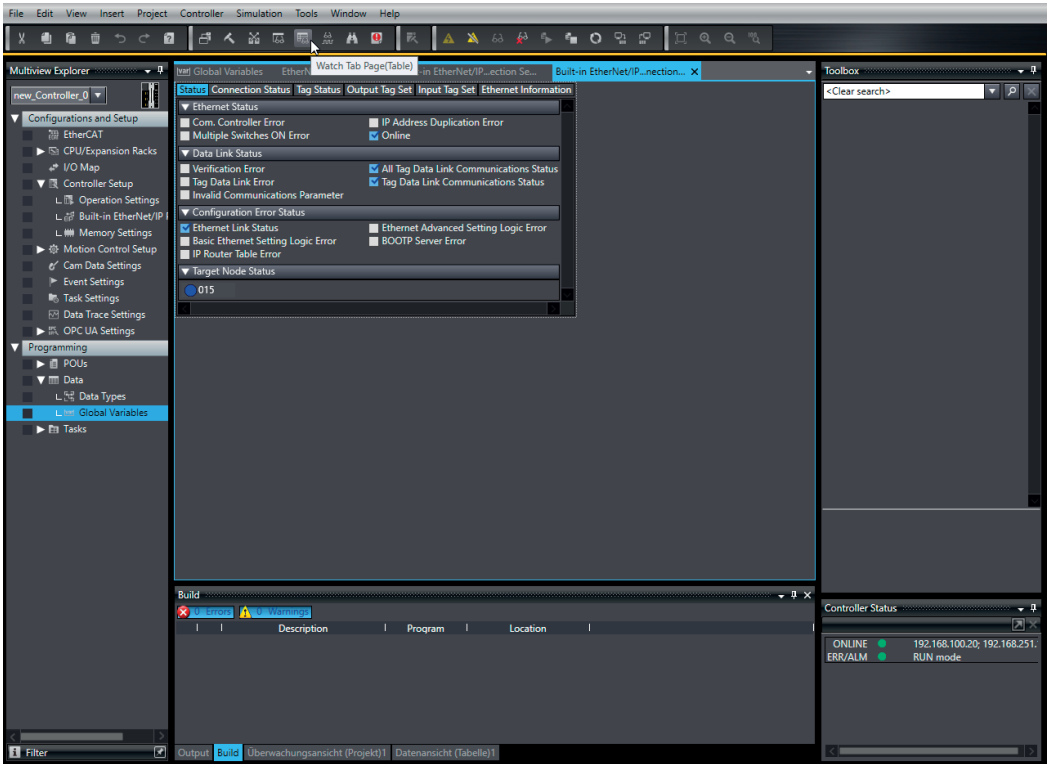
Click on "Monitor" at the relevant IP address to check the connection status.



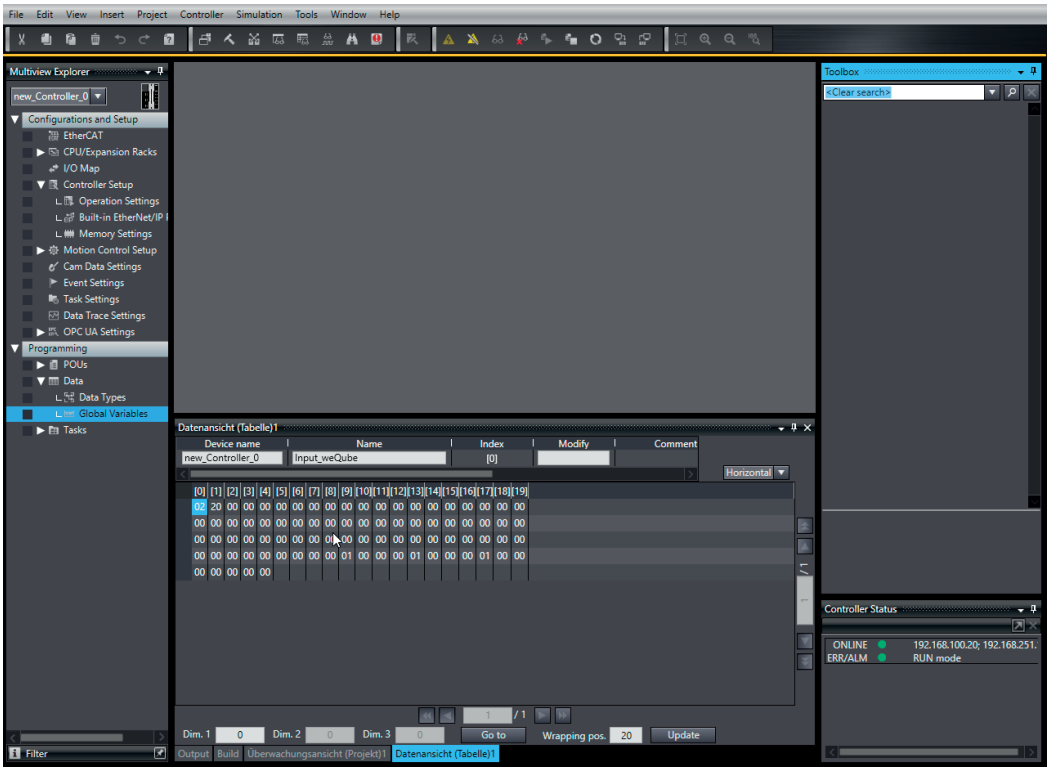
The blue LED shows that the connection from the PLC to the Smart Camera is ok.



Open "Watch Tab Page (Table)" in order to see all input or output bytes.



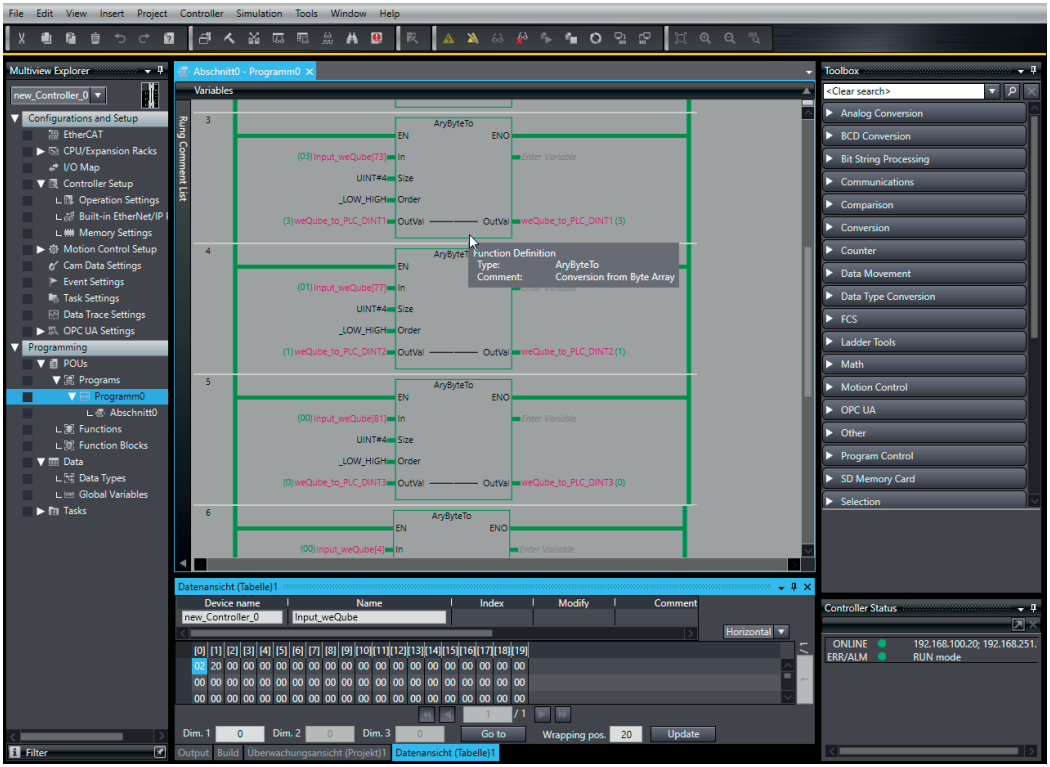
Enter the input or output byte array and check the single byte values.



8.6 PLC Variables

In order to create variables out of the single bytes open "Programs" -> "Program0" -> "Section0". Add the function "AnyByteTo" in order to create DINT, REAL or string values out of the byte array.

The following example shows how to create a DINT result for the Run Counter. The input (In) is set to the start byte value, the size of DINT is UINT#4, the order is "_LOW_HIGH" and a new global variable must be created with data type DINT.



9. Sample PLC program

The download area for the Smart Camera at www.wenglor.com contains sample PLC projects for various controllers. The projects show examples of the required settings on the controller side for Ethernet/IP communication with the weQube Smart Camera.

Samples are available for the following controllers:
- Allen-Bradley 1769-L18ERM BB1B PLC with Studio 5000 Logix Designer V32
- Omron NX102-1200 PLC with Sysmac Studio Version 1.41.0.10
- Beckhoff TwinCAT 3

How to use the sample PLC programs:
1. Download the sample file from the wenglor website and unzip it.
2. Open the associated uniVision project file in the Smart Camera, save it as a start-up project, and restart the Smart Camera. The following slot configuration is used in uniVision projects:

For Studio 5000 (Rockwell):
- Slot 3: 1-byte output
- Slot 4: 1-byte input
- Slot 5: 32-byte input
- Slot 6: 16-byte input (4 DINT)

For Sysmac Studio (Omron):
- Slot 3: 1-byte output
- Slot 4: 1-byte input
- Slot 5: 64-byte input
- Slot 6: 16-byte input (4 DINT)

For TwinCAT 3 (Beckhoff):
- Slot 3: 1-byte output
- Slot 4: 1-byte input
- Slot 5: 16-byte input (4 REAL)
- Slot 6: 16-byte input (4 DINT)

3. Open the sample PLC program, adjust the network configuration, and transfer the program to the PLC, or activate it on the PLC.